

Cartan's equivalence method and non-commutative derivations

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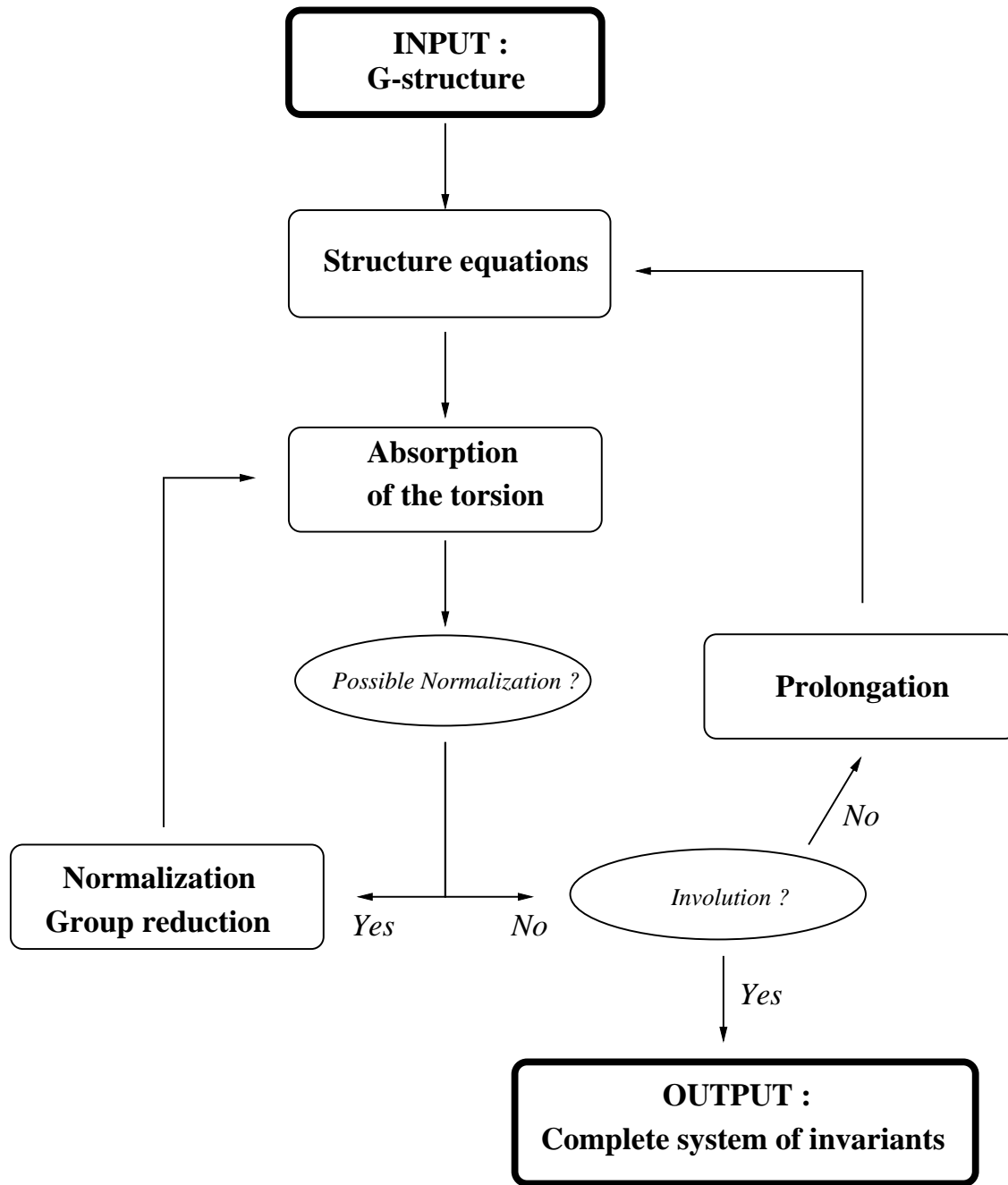
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Plan

- Necessary and sufficient conditions for the linearization of a third order ODE,
- Classification results for some PDE systems.
- Main optimizations of our implementation of the Cartan's equivalence method.

Introduction

- The Cartan's equivalence method allows to decide if two differential equations (or systems of differential equations) are equivalent under the action of a given group of transformation.
- Input of the algorithm : Two differential equations and a group of transformations.
- Output of the algorithm : A complete system of fundamental invariants associated to the equivalence problem.
- See Olver (Equivalence, Invariants and Symmetry). See Cartan, Chern (Third order ODE), Gardner, Olver, Kamran, Fels.



Equivalence of third order ODE's

- Let $x := (x, y, p = y', q = y'') \in \mathbb{R}^4$ be a system of local coordinates of J^2 . Two equations $y_{xxx} = f(x, y, p, q)$ and $\bar{y}''' = \bar{f}(\bar{x}, \bar{y}, \bar{y}', \bar{y}'')$ are equivalent by a contact transformation $\bar{x} = \phi(x)$ when there exist functions (a_1, \dots, a_9) from J^2 to \mathbb{R} such that

$$\phi^* \begin{pmatrix} d\bar{q} - \bar{f}(\bar{x})d\bar{x} \\ d\bar{y} - \bar{p}d\bar{x} \\ d\bar{p} - \bar{q}d\bar{x} \\ d\bar{x} \end{pmatrix} = \underbrace{\begin{pmatrix} a_1(x) & a_2(x) & a_3(x) & 0 \\ 0 & a_4(x) & 0 & 0 \\ 0 & a_5(x) & a_6(x) & 0 \\ 0 & a_7(x) & a_8(x) & a_9(x) \end{pmatrix}}_{\theta(x)} \underbrace{\begin{pmatrix} dq - f(x)dx \\ dy - pdx \\ dp - qdx \\ dx \end{pmatrix}}_{\omega(x)}$$

- The computation splits into two branches depending on the value of

$$I = -\frac{1}{3}f_p f_q + \frac{1}{2}D_x f_p - \frac{1}{6}D_x^2 f_q - f_y + \frac{1}{3}f_q D_x f_q - \frac{2}{27}f_q^3$$

where $D_x := \partial/\partial x + p \partial/\partial y + q \partial/\partial p + f(x, y, p, q) \partial/\partial q$.

Third order ODE's : the case $I = 0$

The final structure equations containing 9 fundamental invariants are :

$$\left\{ \begin{array}{l} d\theta^1 = -\theta^1 \wedge \theta^5 - \theta^3 \wedge \theta^6, \\ d\theta^2 = -\theta^2 \wedge \theta^5 - 2\theta^2 \wedge \theta^9 - \theta^3 \wedge \theta^4, \\ d\theta^3 = -\theta^1 \wedge \theta^4 - \theta^2 \wedge \theta^6 - \theta^3 \wedge \theta^5 - \theta^3 \wedge \theta^9, \\ d\theta^4 = -\theta^2 \wedge \theta^7 - \theta^3 \wedge \theta^8 - \theta^4 \wedge \theta^9, \\ d\theta^5 = -2\theta^1 \wedge \theta^8 - \theta^3 \wedge \theta^7 - \theta^4 \wedge \theta^6, \\ d\theta^6 = -\theta^1 \wedge \theta^7 - \theta^3 \wedge \theta^{10} + \theta^6 \wedge \theta^9, \\ d\theta^7 = I_1\theta^1 \wedge \theta^2 + I_2\theta^1 \wedge \theta^3 + I_3\theta^2 \wedge \theta^3 - \theta^4 \wedge \theta^{10} - \theta^5 \wedge \theta^7 \\ \quad - \theta^6 \wedge \theta^8 + \theta^7 \wedge \theta^9, \\ d\theta^8 = I_4\theta^1 \wedge \theta^2 + I_5\theta^1 \wedge \theta^3 + I_6\theta^2 \wedge \theta^3 - \theta^4 \wedge \theta^7 - \theta^5 \wedge \theta^8, \\ d\theta^9 = \theta^1 \wedge \theta^8 - \theta^2 \wedge \theta^{10} + \theta^4 \wedge \theta^6, \\ d\theta^{10} = I_7\theta^1 \wedge \theta^2 + I_8\theta^1 \wedge \theta^3 + I_9\theta^2 \wedge \theta^3 - \theta^5 \wedge \theta^{10} \\ \quad - \theta^6 \wedge \theta^7 - 2\theta^9 \wedge \theta^{10}. \end{array} \right. \quad (1)$$

Third order ODE's : the case $I = 0$

Theorem 1 Consider the equation $y_{xxxx} = f(x, y, p, q)$. Then the three following conditions are equivalent :

- (i) The equation is equivalent to $y''' = 0$ by a contact transformation.
- (ii) The equation admits a 10 parameters contact symmetry group.
- (iii) $I = 0$ et $f_{qqqq} = 0$.

•The Poincaré's identity

$$d(d\theta^i) = R_{j,k,l}^i \theta^j \wedge \theta^k \wedge \theta^l = 0$$

gives the following differential relations between the invariants :

$$\begin{aligned} -I_2 + I_4 &= 0, & I_1 + 2I_6 &= 0, & \frac{\partial I_3}{\partial \theta^4} + I_9 &= 0, \\ \frac{\partial I_4}{\partial \theta^4} - I_6 + I_1 &= 0, & \frac{\partial I_5}{\partial \theta^4} + I_4 + I_2 &= 0, & \frac{\partial I_6}{\partial \theta^4} + I_3 &= 0, \\ -I_6 - I_8 &= 0, & \frac{\partial I_8}{\partial \theta^4} + I_7 &= 0. \end{aligned}$$

• From the above relations we deduce that $I_5 = -f_{qqqq}/(6a_1^3 a_9)$ is a base of the differential algebra generated by the nine invariants.

Third order ODE's : the case $I \neq 0$

The final structure equations containing 16 fundamental invariants are :

$$\left\{ \begin{array}{l} d\theta^1 = -\theta^1 \wedge \theta^5 + I_1 \theta^2 \wedge \theta^3 + \theta^2 \wedge \theta^4 + I_2 \theta^3 \wedge \theta^4, \\ d\theta^2 = I_3 \theta^2 \wedge \theta^3 - \theta^2 \wedge \theta^5 - \theta^3 \wedge \theta^4, \\ d\theta^3 = I_4 \theta^1 \wedge \theta^2 - \theta^1 \wedge \theta^4 + I_5 \theta^2 \wedge \theta^3 + I_6 \theta^2 \wedge \theta^4 - \theta^3 \wedge \theta^5, \\ d\theta^4 = I_7 \theta^1 \wedge \theta^2 + I_8 \theta^1 \wedge \theta^3 + I_9 \theta^2 \wedge \theta^3 + I_{10} \theta^2 \wedge \theta^4, \\ d\theta^5 = I_{11} \theta^1 \wedge \theta^2 + I_{12} \theta^1 \wedge \theta^3 + I_{13} \theta^1 \wedge \theta^4 + I_{14} \theta^2 \wedge \theta^3 \\ \quad + I_{15} \theta^2 \wedge \theta^4 + I_{16} \theta^3 \wedge \theta^4. \end{array} \right. \quad (2)$$

Third order ODE's : the case $I \neq 0$

In this case, the differential algebra of the invariants I_1, \dots, I_{16} is generated by the four invariants : (I_8, I_3, I_{10}, I_2) .

Theorem 2 *A third order differential equation $y_{xxx} = f(x, y, p, q)$ is equivalent to $y_{xxx} = y$ under the group of contact transformations if and only if :*

$$\left\{ \begin{array}{l} J_{qq} = 0, \\ -4J_q f_q J + f_{qq}(J)^2 - 6J_p J + 6J_q D_x J = 0, \\ D_x J_p - D_x^2 J_q - J_y = 0, \\ -3(J)^2 f_p - (J)^2 f_q^2 + 3(J)^2 D_x f_q - 6J D_x^2 J + 9(D_x J)^2 = 0, \end{array} \right.$$

where $J^3 = I$.

Third order ODE's : linearization conditions

- We used the above invariants to find necessary and sufficient condition so that the equation $y''' = f(x, y, y', y'')$ is equivalent to the linear equation

$$y''' + a(x) y'' + b(x) y' + c(x) y = 0$$

by a contact transformation.

- Case $I = 0$

For a linear equation, we have $f_{qqqq} = 0$. Therefore, every linear equation for which $I = 0$ is equivalent to $y''' = 0$. Then if $I = 0$, a differential equation is linearizable if and only if it is equivalent to $y''' = 0$, i.e $f_{qqqq} = 0$.

Third order ODE's : linearization conditions

- Case $I \neq 0$

Theorem 3 Consider $y''' = f(x, y, y', y'')$, a third order ordinary differential equation such that $I \neq 0$. Then the five following conditions are equivalent :

(i) The equation is equivalent to the linear equation

$$y''' + a(x) y'' + b(x) y' + c(x) y = 0.$$

by a contact transformation.

- (ii) The equation is equivalent to the canonical form $y''' + 2I_2(x) y' + (1 + I_2'(x)) y = 0$ by a contact transformation.
- (iii) The invariants $(I_1, I_2, \dots, I_{16})$ defined in (2), excepted eventually I_2 , are zero.
- (iv) The invariants $(I_1, I_3, I_8, I_{10}, I_{16})$ defined in (2) are zero.
- (v) The 2-forms $d\theta^4$ and $d\theta^5$ defined in (2) are zero.

Second order PDE systems with two independent variables

- We have computed the invariants for the classification of second order pde systems

$$\begin{cases} u_{x^1x^1} = f_{11}(x^1, x^2, u, u_{x^1}, u_{x^2}) \\ u_{x^1x^2} = f_{12}(x^1, x^2, u, u_{x^1}, u_{x^2}) \\ u_{x^2x^2} = f_{22}(x^1, x^2, u, u_{x^1}, u_{x^2}) \end{cases} \quad (3)$$

with one dependent variable u and two independent variables x^1, x^2 under the group of point transformations $\mathbb{R}^3 \ni (x^1, x^2, u) \rightarrow (\bar{x}^1, \bar{x}^2, \bar{u}) \in \mathbb{R}^3$.

- One can show that (3) is equivalent to the flat system

$$u_{x^1x^1} = u_{x^1x^2} = u_{x^2x^2} = 0$$

if and only if all the fundamental invariants are zero.

- These very large invariants occupy 1.1 Mega-bytes of memory. Using our software, we automatically prove that these equivalence conditions are reduced to the vanishing of a very small invariant.

Second order PDE systems with two independent variables

Theorem 4 *The three following conditions are equivalent :*

- (i) *The system (3) can be mapped to the flat system $u_{xx} = u_{xy} = u_{yy} = 0$ by a point transformation.*
- (ii) *The system (3) admits a 15 parameters point symmetry group*
- (iii) *The functions f_{11} , f_{12} and f_{22} of (3) verify the following linear conditions :*

$$\left\{ \begin{array}{l} \frac{\partial^2 f_{11}}{\partial u_2 \partial u_2} = 0, \\ \frac{\partial^2 f_{22}}{\partial u_1 \partial u_1} = 0, \\ \frac{\partial^2 f_{12}}{\partial u_2 \partial u_2} - \frac{\partial^2 f_{11}}{\partial u_1 \partial u_2} = 0, \\ \frac{\partial^2 f_{12}}{\partial u_1 \partial u_1} - \frac{\partial^2 f_{22}}{\partial u_1 \partial u_2} = 0, \\ \frac{\partial^2 f_{11}}{\partial u_1 \partial u_1} - 4 \frac{\partial^2 f_{12}}{\partial u_1 \partial u_2} + \frac{\partial^2 f_{22}}{\partial u_2 \partial u_2} = 0. \end{array} \right.$$

Our Maple implementation of Cartan's equivalence method

- All the computations are done using non-commutative derivations. These derivations are dual of the forms ω^i . Such derivations naturally compress the invariants.

Example	use of $\partial/\partial x^i$	use of $\partial/\partial \omega^i$
$y''' = f, I = 0$	18 Kb (35 sec)	8 Kb (20 sec)
$y''' = f, I \neq 0$	57 Kb (7 sec)	7, 5 Kb (3, 5 sec)
$y^{(4)} = f$	280 Kb (38 sec)	36 Kb (9 sec)
PDE system (3)	Does not finish	1, 1 Mb (3 h)

- The Poincaré's identity, $d(d\theta^i) = 0$, is automatically performed. It generates a lot of differential relations between the invariants.
- These relations are used to compute a base of the differential ideal or differential algebra of the invariants. It allows a great simplification of the equivalence conditions.
- You can find this 4500 lines maple package at www.lifl.fr/~neut.