

The Variational Bicomplex

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The first main application of the variational bicomplex is to provide a natural geometric context for the calculus of variations. However, applications extend to the general theory of conservation laws for PDE, characteristic classes, Gelfand-Fuks cohomology and more things I don't know anything about.

The Variational Bicomplex!!!

$$\begin{array}{ccccccccccc}
 & & \vdots & & \vdots & & \vdots & & \vdots & & \vdots \\
 & & d_V \uparrow & & d_V \uparrow & & d_V \uparrow & & d_V \uparrow & & \delta_V \uparrow \\
 0 & \longrightarrow & \Omega^{0,3} & \xrightarrow{d_H} & \Omega^{1,3} & \xrightarrow{d_H} & \dots & \xrightarrow{d_H} & \Omega^{p-1,3} & \xrightarrow{d_H} & \Omega^{p,3} & \xrightarrow{\pi} & \mathcal{F}^3 & \longrightarrow & 0 \\
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 & & & & & & & & & & & & & & \nearrow E
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Conservation Laws,

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Conservation Laws, Lagrangians, Euler-Lagrange Eqns,

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Conservation Laws, Lagrangians, Euler-Lagrange Eqns, Helmholtz Conds

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$\pi : M \rightarrow X$ will be a **fiber bundle** or more generally a fibered manifold.

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For purely local considerations, we may assume $M = X \times U$ where
 $X = \mathbb{R}^p$ with coordinates $\mathbf{x} = (\mathbf{x}^1, \dots, \mathbf{x}^p)$ (*independent variables*)
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When there are only a few independent or dependent variables, we'll use \mathbf{t} or $\mathbf{x}, \mathbf{y}, \mathbf{z}$ and \mathbf{u}, \mathbf{v} instead of the above.

Multi-index notation will be used for partial derivatives. If $J = (j_1, \dots, j_k)$, $1 \leq j_\nu \leq p$, we write $|J| = k$ and

$$\mathbf{u}_J^\alpha = \mathbf{u}_{j_1 \dots j_k}^\alpha = \frac{\partial^k \mathbf{u}^\alpha}{\partial \mathbf{x}^{j_1} \dots \partial \mathbf{x}^{j_k}}$$

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Unless noted otherwise, multi-indices will be **symmetric**, i.e. $J_1 = J_2$ if one is a reordering of the other. This reflects equality of mixed partials.

Finite Order Jet Bundles

Let $x \in X$,
declare two sections s_1 and s_2 to have **n^{th} order contact at x** if all partial derivatives up to order n of s_1 and s_2 agree at x .
This is an equivalence relation on sections.

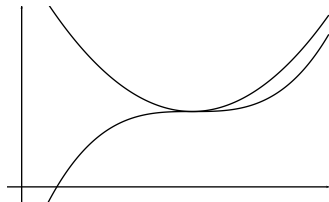


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Denote by $\mathbf{j}_n \mathbf{s}|_x$ the equivalence class of s : the **n -jet of s at x** . The n -jets constitute a bundle over M , the **jet bundle $J^n(M)$** .
 The jet $\mathbf{j}_n \mathbf{s}$ is a section of this bundle.

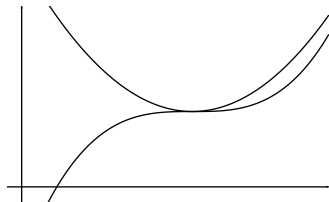


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Adapted local coordinates (x, u) on M induce **local coordinates**
 $(x, u, \dots, u^J, \dots) = (x, \mathbf{u}^{(n)})$ on $J^n(M)$, $|J| \leq n$.

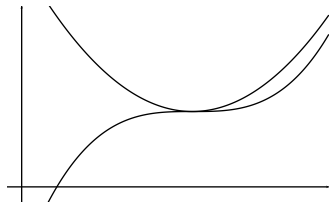


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Example

Coordinates (x, y, u) on the bundle $\mathbb{R}^2 \times \mathbb{R} \rightarrow \mathbb{R}^2$ induce coordinates $(x, y, u^{(2)}) = (x, y, u, u_x, u_y, u_{xx}, u_{xy}, u_{yy})$ on $J^2(\mathbb{R}^2 \times \mathbb{R})$.

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Specifying a section s of $\mathbb{R}^2 \times \mathbb{R} \rightarrow \mathbb{R}^2$ is tantamount to specifying a function $f : \mathbb{R}^2 \rightarrow \mathbb{R}$:

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The jet of this section is obtained by differentiating f :

$$j_2 s|_{(x_0, y_0)} = \left(x, y, f, \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial^2 f}{\partial x^2}, \frac{\partial f}{\partial y \partial x}, \frac{\partial^2 f}{\partial y^2} \right) \Big|_{(x_0, y_0)}$$

Variational Calculus

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Let R be a connected region in X with smooth boundary.

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Fundamental problem of variational calculus

Find the **extrema of the functional**

$$\mathcal{L}[u] = \int_R L(x, u^{(n)}) dx$$

over some class of functions $u = f(x)$.

Example (Minimizing Arclength)

Take $X = \mathbb{R}$ (with coordinate t) and $U = \mathbb{R}^2$ (with coordinates u, v).

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We search for extrema of \mathcal{L} over functions $(u(t), v(t))$ with fixed endpoints.

One expects that a minimum will be a straight line connecting the fixed endpoints. We'll return to this example shortly.

Total Derivatives

Given $F(x, u^{(n)})$ one can “pretend” u is a function of x and take a partial derivative w.r.t. x^j . The result is the **total derivative** $D_{x^j}F$ or D_jF :

$$D_jF = \frac{\partial F}{\partial x^j} + \sum_{\alpha, J} u_{Jj}^\alpha \frac{\partial F}{\partial u_j^\alpha} \quad \text{where } u_{Jj}^\alpha = \frac{\partial u_j^\alpha}{\partial x^j}.$$

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Example. With coordinates u and x, y

$$D_x(x^2 + u_y^2) = 2x + 2u_y u_{yx}$$

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NOTE: D_j raises the order of F by 1.

Euler-Lagrange Equations

To find extrema perform a **variation of u** : let u_ϵ be a family of functions which agree outside a compact $K \subset R$. If $u_0 = u$ is an extremal, then

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Because of agreement outside K , integrate by parts and the boundary term is zero: $\int_R \frac{\partial L}{\partial u_J^\alpha} D_J v^\alpha dx = \int_R (-D)_J \left(\frac{\partial L}{\partial u_J^\alpha} \right) v^\alpha dx$.

$$\text{Thus } 0 = \int_R \left\{ \sum_{\alpha} \sum_J (-D)_J \frac{\partial L}{\partial u_J^\alpha} v^\alpha \right\} dx$$

Each v^α is (essentially) arbitrary, so **an extremum u must satisfy** the

$$\text{Euler-Lagrange equations } E_\alpha L = \sum_J (-D)_J \frac{\partial L}{\partial u_J^\alpha} = 0$$

Example (Minimizing Arclength Revisited)

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We look at the first equation (the second follows by symmetry):

$$\begin{aligned} (-D)_t \frac{\partial L}{\partial u_t} &= -D_t [u_t (u_t^2 + v_t^2)^{-1/2}] \\ &= -u_{tt} \left[(u_t^2 + v_t^2)^{-1/2} - u_t^2 (u_t^2 + v_t^2)^{-3/2} \right] \\ &= \frac{-u_{tt}}{(u_t^2 + v_t^2)^{1/2}} \left[1 - \frac{u_t^2}{u_t^2 + v_t^2} \right] \end{aligned}$$

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Thus the Euler-Lagrange equations are satisfied iff

$$(u_{tt} = 0 \text{ or } v_t = 0) \text{ and } (v_{tt} = 0 \text{ or } u_t = 0)$$

Differential Forms on Finite Order Jet Bundles

A **basic differential k -form** on $J^n(M)$ has a local coordinate expression

$$F(\mathbf{x}, \mathbf{u}^{(n)}) dx^{i_1} \wedge \cdots \wedge dx^{i_a} \wedge du_{J_1}^{\alpha_1} \wedge \cdots \wedge du_{J_b}^{\alpha_b} \quad \text{where } a + b = k.$$

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Important are the **basic contact one-forms**, for $|J| \leq n - 1$ given by

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Let $u = f(x, y)$ (i.e. pull back by the section $s(x) = (x, y, f(x, y))$), then

$$(j_2 s)^* \theta_x = d\left(\frac{\partial f}{\partial x}\right) - \frac{\partial^2 f}{\partial x^2} dx - \frac{\partial^2 f}{\partial x \partial y} dy = 0$$

Infinite Order Jet Bundles

Since n^{th} order contact $\implies k^{\text{th}}$ order contact for $k \leq n$, there are natural projections

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Smooth functions on $J^\infty(M)$ factor through some finite order $J^n(M)$:

$$F : J^\infty \rightarrow \mathbb{R} \implies F = f \circ \pi_n^\infty \text{ for some smooth } f : J^n \rightarrow \mathbb{R}$$

Write $\mathbf{F}[\mathbf{x}, \mathbf{u}]$ for a function on $J^\infty(M)$.

Differential Forms on Infinite Order Jet Bundles

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→ From now on we write J^n or J^∞ instead of $J^n(M)$ or $J^\infty(M)$.

The Bigrading on $\Omega^*(J^\infty)$

We can define **basic contact forms** in $\Omega^1(J^\infty)$ without restriction on $|J|$:

$$\theta_j^\alpha = du_j^\alpha - \sum_j u_{j^2}^\alpha dx^j$$

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An arbitrary form in $\Omega^k(J^\infty)$ is a linear combination of the **new basic k -forms**

$$F[x, u] dx^{i_1} \wedge \cdots \wedge dx^{i_r} \wedge \theta_{J_1}^{\alpha_1} \wedge \cdots \wedge \theta_{J_s}^{\alpha_s} \quad (*)$$

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where $r + s = k$.

Now, fix r, s . Define the space $\Omega^{r,s}(J^\infty)$ of forms of type (r, s) to be all linear combinations of expressions of the form (\star) .

“All forms which are a sum of wedges of r dx^j 's and s $\theta_j^{\alpha_i}$'s”

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“All forms which are a sum of wedges of r dx^j 's and s θ_j^α 's”

$\Omega^*(J^\infty)$ is a direct sum (the **bigrading** on $\Omega^*(J^\infty)$):

$$\Omega^*(J^\infty) = \bigoplus_{r,s} \Omega^{r,s}(J^\infty)$$

Example (rewriting a form in terms of the bigrading)

Consider $\mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}^2$ with coordinates x, y and u^1, u^2 . We choose a form on $J^\infty(\mathbb{R}^2 \times \mathbb{R}^2)$, and write it in terms of the bigrading:

$$\begin{aligned} dx \wedge du_x^1 \wedge du^2 &= dx \wedge (\theta_x^1 + u_{xx}^1 dx + u_{xy}^1 dy) \wedge (\theta^2 + u_x^2 dx + u_y^2 dy) \\ &= dx \wedge \theta_x^1 \wedge \theta^2 + u_y^2 dx \wedge \theta_x^1 \wedge dy + u_{xy}^1 dx \wedge dy \wedge \theta^2 \end{aligned}$$

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Thus $dx \wedge du_x^1 \wedge du^2 \in \Omega^{1,2} \oplus \Omega^{2,1}$ since

$$dx \wedge \theta_x^1 \wedge \theta^2 \in \Omega^{1,2}$$

and

$$u_y^2 dx \wedge \theta_x^1 \wedge dy \text{ and } u_{xy}^1 dx \wedge dy \wedge \theta^2 \in \Omega^{2,1}$$

Splitting of the Exterior Derivative

Let $F[x, u]$ be a function on J^∞ . The **exterior derivative** is defined as usual:

$$dF = \sum_j \frac{\partial F}{\partial x^j} dx^j + \sum_\alpha \sum_J \frac{\partial F}{\partial u_J^\alpha} du_J^\alpha$$

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We can write dF using contact forms and the total derivative:

$$\begin{aligned} dF &= \sum_j \frac{\partial F}{\partial x^j} dx^j + \sum_\alpha \sum_J \frac{\partial F}{\partial u_J^\alpha} du_J^\alpha \\ &= \sum_j \left(\frac{\partial F}{\partial x^j} + \sum_\alpha \sum_J u_{Jj}^\alpha \frac{\partial F}{\partial u_J^\alpha} \right) dx^j + \sum_\alpha \sum_J \frac{\partial F}{\partial u_J^\alpha} \theta_J^\alpha \\ &= \sum_j D_j F dx^j + \sum_\alpha \sum_J \frac{\partial F}{\partial u_J^\alpha} \theta_J^\alpha \end{aligned}$$

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Define

$$\mathbf{d}_H F = \sum_j D_j F dx^j \quad \text{and} \quad \mathbf{d}_V F = \sum_\alpha \sum_J \frac{\partial F}{\partial u_J^\alpha} \theta_J^\alpha$$

Splitting of the Exterior Derivative, Continued

Starting with $F \in \Omega^{0,0}$ we found $dF = d_H F + d_V F$, where

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In general, for $\omega \in \Omega^{r,s}$, there is a splitting $d\omega = d_H \omega + d_V \omega$, where

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Example. Consider $\theta_j^\alpha \in \Omega^{0,1}$. Then $d_H \theta_j^\alpha = -\sum_j \theta_{jj}^\alpha \wedge dx^j$ and $d_V \theta_j^\alpha = 0$. To see this, compute:

$$\begin{aligned} d\theta_j^\alpha &= d\left(du_j^\alpha - \sum_j u_{jj}^\alpha dx^j\right) \\ &= -\sum_j du_{jj}^\alpha \wedge dx^j \\ &= -\sum_j \theta_{jj}^\alpha \wedge dx^j + \sum_{i,j} u_{jj,i}^\alpha dx^i \wedge dx^j \\ &= -\sum_j \theta_{jj}^\alpha \wedge dx^j \end{aligned}$$

Building the Bicomplex

By virtue of $\mathbf{d}^2 = \mathbf{0}$ we have $\mathbf{d}_H^2 = \mathbf{0}$, $\mathbf{d}_V^2 = \mathbf{0}$ and $\mathbf{d}_H \mathbf{d}_V = -\mathbf{d}_V \mathbf{d}_H$.

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$$\Omega^{0,s} \xrightarrow{d_H} \Omega^{1,s} \xrightarrow{d_H} \Omega^{2,s} \xrightarrow{d_H} \dots \xrightarrow{d_H} \Omega^{n,s}$$

is a complex, and for fixed r

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is a complex. In summary we have a **bicomplex** of differential forms:

$$\begin{array}{ccccccc}
 & \vdots & & \vdots & & \dots & & \vdots & & \vdots \\
 & \uparrow d_V & & \uparrow d_V & & & & \uparrow d_V & & \uparrow d_V \\
 \Omega^{0,1} & \xrightarrow{d_H} & \Omega^{1,1} & \xrightarrow{d_H} & \dots & \xrightarrow{d_H} & \Omega^{p-1,1} & \xrightarrow{d_H} & \Omega^{p,1} \\
 & \uparrow d_V & & \uparrow d_V & & & \uparrow d_V & & \uparrow d_V \\
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 \end{array}$$

Building the Bicomplex, Continued

Let's take a closer look at the bottom right edge of the bicomplex.

$$\begin{array}{ccc} \dots & \xrightarrow{d_H} & \Omega^{p,1} \\ & & \uparrow d_V \\ \dots & \xrightarrow{d_H} & \Omega^{p,0} \end{array}$$

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Each element of $\Omega^{p,0}$ has the form $L[x, u]dx^1 \wedge \dots \wedge dx^p = L dx$ and so can be interpreted as the **Lagrangian** for a variational problem.

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Let's try to interpret d_V of our Lagrangian:

$$d_V(L[x, u]dx^1 \wedge \dots \wedge dx^p) = \sum_{\alpha, J} \frac{\partial L}{\partial u_J^\alpha} \theta_J^\alpha \wedge dx^1 \wedge \dots \wedge dx^p$$

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Notice the similarity with the variational derivative:

$$d_V(Ldx) = \sum_{\alpha, J} \frac{\partial L}{\partial u_J^\alpha} \theta_J^\alpha \wedge dx \quad \leftrightarrow \quad \left. \frac{d\mathcal{L}[u_\epsilon]}{d\epsilon} \right|_{\epsilon=0} = \int_R \left\{ \sum_{\alpha, J} \frac{\partial L}{\partial u_J^\alpha} D_J v^\alpha \right\} dx$$

Integration by Parts

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First way: quotient by the image of d_H : $\Omega^{p-1,1} \rightarrow \Omega^{p,1}$.

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First way: quotient by the image of d_H : $\Omega^{p-1,1} \rightarrow \Omega^{p,1}$.

To see this, let $\eta^j = dx^1 \wedge \cdots \wedge \widehat{dx^j} \wedge \cdots \wedge dx^p$ and compute

$$\begin{aligned}
 & d_H(P[x, u]\theta_j^\alpha \wedge \eta^j) \\
 &= \left(\sum_i D_i P dx^i \right) \wedge \theta_j^\alpha \wedge \eta^j + P \wedge \left(- \sum_i \theta_{j_i}^\alpha \wedge dx^i \right) \wedge \eta^j \\
 &= D_j P dx^j \wedge \theta_j^\alpha \wedge \eta^j - P \theta_{j_j}^\alpha \wedge dx^j \wedge \eta^j \\
 &= (-1)^j \left[D_j P \theta_j^\alpha \wedge dx + P \theta_{j_j}^\alpha \wedge dx \right]
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We’ll save the **second way** for another talk.

The Euler Operator

Using \equiv for equivalence modulo $\text{Im } d_H$, we find

$$\begin{aligned}
 d_V(Ldx) &= \sum_{\alpha, J} \frac{\partial L}{\partial u_J^\alpha} \theta_J^\alpha \wedge dx \\
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$$\pi(d_V(Ldx)) \equiv \sum_{\alpha} E_\alpha(L) \theta^\alpha \wedge dx$$

We write $\pi \circ d_V = \mathbf{E}$ and call E the **Euler operator**.

Building the Bicomplex, Continued

We build \mathcal{F}^1 and the Euler operator E into our bicomplex:

$$\begin{array}{ccccc} & & \vdots & & \\ & & \uparrow d_V & & \\ \dots & \xrightarrow{d_H} & \Omega^{p,1} & \xrightarrow{\pi} & \mathcal{F}^1 \\ & & \uparrow d_V & \nearrow E & \\ \dots & \xrightarrow{d_H} & \Omega^{p,0} & & \end{array}$$

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In analogy with \mathcal{F}^1 , define $\mathcal{F}^s = \Omega^{p,s} / \text{Im } d_H$, a space which will allow us to perform “higher order integration by parts”.

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Use d_V to define $\delta_V : \mathcal{F}^s \rightarrow \mathcal{F}^{s+1}$ by mapping equivalence representatives:

$$\delta_V(\omega + \text{Im } d_H) = d_V\omega + \text{Im } d_H$$

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Since $d_V d_H = -d_H d_V$, δ_V is well-defined, and since $d_V^2 = 0$, $\delta_V^2 = 0$.

Building the Bicomplex, almost done

We can now incorporate \mathcal{F}^s and δ_V into our bicomplex:

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The edge of this bicomplex is of particular interest, and is called the **Euler-Lagrange complex**.

The Euler-Lagrange Complex

Theorem. The cohomology of the Euler-Lagrange complex is equal to the de Rham cohomology of M . In particular, if $M = \mathbb{R}^p \times \mathbb{R}^q$, the **Euler-Lagrange complex is exact**.

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Let's examine an easy consequence: suppose that L is such that the Euler-Lagrange equations are automatically satisfied. Thus $E(L dx) = 0$. By exactness, this means that $L dx = d_H \omega$ for some $\omega \in \Omega^{n-1,0}$.

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A general $\omega \in \Omega^{p-1,0}$ has the form $\sum_j P_j[x, u] \eta^j$, so

$$d_V(L dx) = 0 \iff d_H \omega = L dx \iff L = \sum_j (-1)^{j-1} D_j P_j dx$$

Thus L is a **null Lagrangian** if and only if $L = \sum_j D_j \left((-1)^{j-1} P_j \right)$

Concluding Remarks