

A CONFORMAL DIFFERENTIAL INVARIANT AND THE CONFORMAL RIGIDITY OF HYPERSURFACES

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ABSTRACT. For a hypersurface V^{n-1} of a conformal space, we introduce a conformal differential invariant $I = \frac{h^2}{g}$, where g and h are the first and the second fundamental forms of V^{n-1} connected by the apolarity condition. This invariant is called the *conformal quadratic element* of V^{n-1} . The solution of the problem of conformal rigidity is presented in the framework of conformal differential geometry and connected with the conformal quadratic element of V^{n-1} . The main theorem states:

Let $n \geq 4$, and let V^{n-1} and \bar{V}^{n-1} be two nonisotropic hypersurfaces without umbilical points in a conformal space C^n or a pseudoconformal space C_q^n of signature (p, q) , $p = n - q$. Suppose that there is a one-to-one correspondence $f : V^{n-1} \rightarrow \bar{V}^{n-1}$ between points of these hypersurfaces, and in the corresponding points of V^{n-1} and \bar{V}^{n-1} the following condition holds: $\bar{I} = f_*I$, where $f_* : T(V^{n-1}) \rightarrow T(\bar{V}^{n-1})$ is a mapping induced by the correspondence f . Then the hypersurfaces V^{n-1} and \bar{V}^{n-1} are conformally equivalent.

1. In local differential geometry the rigidity theorems contain conditions under which two submanifolds of a homogeneous space can differ only by a location in the space. For hypersurfaces in a projective space, the rigidity problem was considered by G. Fubini [6, 7] (see also pp. 605–629 of the book [8] by Fubini and E. Čech), É. Cartan [5], G. Jensen and E. Musso [10], and by the authors of this paper in the book [1] (Section 7.4).

The problem of conformal rigidity of submanifolds is also of great interest. This problem was studied by Cartan [4], M. do Carmo and M. Dajczer [2] and R. Sacksteder [11] (see also the paper [13] by R. Sulanke in which the author considered problems close to the rigidity problem). However, in these papers the problem of conformal rigidity was investigated in the framework of Euclidean geometry.

In the current paper we present the solution of this problem in the framework of conformal differential geometry. To this end, we introduce a conformal quadratic element and prove that if $n \geq 4$ and there exists a one-to-one point correspondence of two hypersurfaces both not having umbilical points preserving this quadratic

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element, then the hypersurfaces are conformally equivalent. Moreover, we consider the rigidity problem not only for hypersurfaces of a conformal space but also for hypersurfaces of a pseudoconformal space. We only assume that a hypersurface is not isotropic (i.e., its tangent subspaces are not tangent to the isotropic cones).

2. Let V^{n-1} be a nonisotropic hypersurface of a real conformal space C^n or a real pseudoconformal space C_q^n of signature (p, q) , where $p = n - q$. With any point $x \in V^{n-1}$, we associate a conformal moving frame consisting of two points $A_0 = x$ and A_{n+1} and n independent hyperspheres A_1, \dots, A_n , passing through these two points. We will assume that the hypersphere A_n is tangent to the hypersurface V^{n-1} at the point A_0 , and the hyperspheres $A_i, i = 1, \dots, n - 1$, are orthogonal to V^{n-1} at the point A_0 . Then the frame elements satisfy the following conditions:

$$(1) \quad \begin{aligned} (A_0, A_0) &= (A_{n+1}, A_{n+1}) = 0, & (A_0, A_i) &= (A_{n+1}, A_i) = 0, \\ (A_0, A_n) &= (A_{n+1}, A_n) = 0, & (A_i, A_n) &= 0, \end{aligned}$$

where the parentheses denote the scalar product of corresponding frame elements. The first two of these conditions mean that the frame elements A_0 and A_{n+1} are points, the following four conditions mean that the hyperspheres A_i and A_n pass through these two points, and finally, the last condition expresses the orthogonality of the hyperspheres A_i and A_n . In addition, we normalize the points A_0 and A_{n+1} by the condition

$$(2) \quad (A_0, A_{n+1}) = -1.$$

We will not demand the orthogonality of the hyperspheres A_i and will write their scalar products in the form:

$$(3) \quad (A_i, A_j) = g_{ij},$$

where $\det(g_{ij}) \neq 0$, since the hypersurface V^{n-1} is not isotropic.

If X is an arbitrary point of the space C^n or the space C_q^n , then it can be represented as

$$X = x^0 A_0 + x^i A_i + x^n A_n + x^{n+1} A_{n+1}.$$

Since for any point $X \in C^n$, we have $(X, X) = 0$, then it follows that the coordinates of the point X satisfy the equation

$$g_{ij} x^i x^j + \epsilon (x^n)^2 - 2x^0 x^{n+1} = 0,$$

where $\epsilon = (A_n, A_n) \neq 0$, since the quadratic form on the left-hand side of the last equation is nondegenerate. The last equation is the equation of a nondegenerate hyperquadric Q^n of a projective space P^{n+1} onto which the space C^n or the space C_q^n is mapped under the Darboux mapping. The left-hand side of this equation is of signature $(p + 1, q + 1)$. Under the Darboux mapping, the images of the points A_0 and A_{n+1} are the points lying on the hyperquadric Q^n , and in general, the images of the hyperspheres A_i and A_n are the points not belonging to Q^n .

We will prove now that the quantity ϵ can be always reduced to 1. In fact, if $\epsilon > 0$, then this can be achieved by means of renormalization of the hypersphere A_n . If $\epsilon < 0$, then we can replace the point A_0 by $-A_0$ which implies

$$g_{ij} x^i x^j + \epsilon (x^n)^2 + 2x^0 x^{n+1} = 0,$$

and then change the sign of the left-hand side of the above equation and again reduce to 1 the positive quantity $-\epsilon$. As a result, the equation of the Darboux

hyperquadric takes the form

$$-g_{ij}x^i x^j + (x^n)^2 - 2x^0 x^{n+1} = 0.$$

By setting $g_{ij} = -\tilde{g}_{ij}$ and suppressing tilde, we reduce the last equation to the form

$$(4) \quad g_{ij}x^i x^j + (x^n)^2 - 2x^0 x^{n+1} = 0.$$

Therefore, for any $\epsilon \neq 0$, we can normalize the hypersphere A_n in such a way that

$$(5) \quad (A_n, A_n) = 1.$$

The form $g_{ij}x^i x^j$ in equation (4) has signature $(p - 1, q)$.

3. The equations of infinitesimal displacement of our conformal frame have the form:

$$(6) \quad dA_\xi = \omega_\xi^\eta A_\eta, \quad \xi, \eta = 0, 1, \dots, n + 1,$$

where ω_ξ^η are 1-forms containing parameters, on which the family of frames in question depends, and their differentials: $\omega_\xi^\eta = \omega_\xi^\eta(u, du)$. By equations (1)–(3) and (5), these forms must satisfy the following conditions:

$$(7) \quad \begin{cases} \omega_0^{n+1} = \omega_{n+1}^0 = 0, & \omega_0^0 + \omega_{n+1}^{n+1} = 0, \\ \omega_i^{n+1} = g_{ij}\omega_0^j, & \omega_{n+1}^i = g^{ij}\omega_j^0, \\ \omega_n^{n+1} = \omega_0^n, & \omega_{n+1}^n = \omega_n^0, \\ \omega_i^n = -g_{ij}\omega_j^n, & \omega_n^n = 0, \\ dg_{ij} = g_{ik}\omega_j^k + g_{kj}\omega_i^k. \end{cases}$$

In addition, the forms ω_ξ^η satisfy the structure equations of the conformal space:

$$(8) \quad d\omega_\xi^\eta = \omega_\xi^\zeta \wedge \omega_\zeta^\eta, \quad \xi, \eta, \zeta = 0, 1, \dots, n + 1.$$

4. Since the hypersphere A_n is tangent to the hypersurface V^{n-1} at the point $x = A_0$, the condition $(A_n, dA_0) = 0$ holds. It follows from this condition that

$$(9) \quad \omega_0^n = 0.$$

This equation determines the family of frames of first order associated with the hypersurface V^{n-1} . This family can be considered as the frame bundle $\mathcal{R}^1(V^{n-1})$ of first order with the base V^{n-1} . Its fiber is a set of frames which is associated with the point $x \in V^{n-1}$ in the manner indicated above. The structure group of the frame bundle $\mathcal{R}^1(V^{n-1})$ is a subgroup of the fundamental group of the space C_q^n whose transformations leave invariant the tangent element of V^{n-1} consisting of a point $x \in V^{n-1}$ and the tangent subspace $T_x(V^{n-1})$. The 1-forms ω_0^i , which we will denote further by ω^i , are basis forms of the frame bundle $\mathcal{R}^1(V^{n-1})$, and the 1-forms $\omega_0^0, \omega_i^0, \omega_n^0$, and ω_j^j are its fiber forms.

By equation (9), on the hypersurface V^{n-1} , we have

$$(10) \quad dA_0 = \omega_0^0 A_0 + \omega^i A_i.$$

By virtue of this,

$$(dA_0, dA_0) = g_{ij}\omega^i \omega^j.$$

The quadratic form $g = g_{ij}\omega^i \omega^j$ is relatively invariant and determines a conformal structure on the hypersurface V^{n-1} . This form is nondegenerate and of signature $(p - 1, q)$. For $q = 0$ (i.e., for the proper conformal space C^n) the form g is positive

definite. For $p = 1$ and $q = n - 1$ (i.e., for a conformal space C_1^m of Lorentzian signature) there exist hypersurfaces with signature $(0, q)$. Such hypersurfaces are called *spacelike*, and a conformal structure induced on them is properly conformal. The equation $g_{ij}\omega^i\omega^j = 0$ determines the isotropic cone of the hypersurface V^{n-1} .

Taking the exterior derivative of equation (9) and applying (8), we obtain

$$(11) \quad \omega^i \wedge \omega_i^n = 0.$$

Applying Cartan's lemma to equation (11), we find that

$$(12) \quad \omega_i^n = \lambda_{ij}\omega^j, \quad \lambda_{ij} = \lambda_{ji}.$$

Differentiating equation (10), we obtain

$$d^2A_0 = (d\omega_0^0 + (\omega_0^0)^2 + \omega_0^i\omega_i^0)A_0 + (\omega_0^0\omega_0^i + \omega_0^j\omega_j^i)A_i + \omega_0^i\omega_i^n A_n + \omega_0^i\omega_i^{n+1} A_{n+1}.$$

It follows that

$$\bar{h} = (d^2A_0, A_n) = \omega^i\omega_n^i = \lambda_{ij}\omega^i\omega^j.$$

In the tangent subspace $T_x(V^{n-1})$, the equation $\bar{h} = 0$ determines the cone of directions along which the hypersphere A_n has a second order tangency with V^{n-1} .

But the quadratic form \bar{h} is not conformally invariant since all hyperspheres of the pencil

$$A'_n = A_n + sA_0$$

as well as the hypersphere A_n are tangent to the hypersurface V^{n-1} . In view of this, we obtain the following pencil of quadratic forms:

$$(d^2A_0, A'_n) = \omega_0^i\omega_i^n - s\omega_0^i\omega_i^{n+1} = (\lambda_{ij} - sg_{ij})\omega^i\omega^j,$$

and all quadratic forms of this pencil have equal rights. From this pencil we will distinguish one form:

$$h = h_{ij}\omega^i\omega^j,$$

where

$$h_{ij} = \lambda_{ij} - \lambda g_{ij} \quad \text{and} \quad \lambda = \frac{1}{n-1}\lambda_{ij}g^{ij}.$$

It is easy to see that the coefficients h_{ij} satisfy the *apolarity condition* (the trace-free condition):

$$(13) \quad h_{ij}g^{ij} = 0,$$

where g^{ij} is the inverse tensor for g_{ij} .

One can prove that geometrically condition (13) means that the cone determined by the equation $h = 0$ is real and there exists an orthogonal $(n - 1)$ -hedron formed by tangent directions to V^{n-1} at the point x which is inscribed into this cone (see [1], pp. 214-216).

The tangent hypersphere $C_n = A_n + \lambda A_0$ is conformally invariant. It is called the *central tangent hypersphere*. The cone $h = 0$ is composed of directions along which the hypersphere C_n has a second order tangency with V^{n-1} .

The quadratic forms g and h are called the *first and second fundamental forms* of the hypersurface V^{n-1} .

Points of the hypersurface V^{n-1} , in which the forms \bar{h} and g are proportional, are called *umbilical points*. It is well-known that if at any point $x \in V^{n-1}$, we have

$\bar{h} = \kappa g$, then the hypersurface V^{n-1} is a hypersphere or its open part. Note that by (13) the condition $\bar{h} = \kappa g$ implies $h = 0$.

If in the frame $\mathcal{R}_x(V^{n-1})$ associated with a point $x \in V^{n-1}$ we replace the tangent hypersphere A_n by the central tangent hypersphere C_n , then we obtain a second order frame $\mathcal{R}_x^2(V^{n-1}) \subset \mathcal{R}^2(V^{n-1})$. Transformations of the structural group of the fibre bundle $\mathcal{R}^2(V^{n-1})$ leave invariant not only the tangent element of the hypersurface V^{n-1} but also the central tangent hypersphere C_n attached to a point $x \in V^{n-1}$. In the fiber bundle $\mathcal{R}^2(V^{n-1})$, the number of fiber forms will be reduced, since the 1-form ω_n^0 becomes a linear combination of the basis forms ω^i .

With respect to a second order frame, equation (12) takes the form

$$(14) \quad \omega_i^n = h_{ij}\omega^j.$$

The point $A_0 \in V^{n-1}$ admits the normalization

$$(15) \quad A'_0 = rA_0, \quad r \neq 0.$$

In order to preserve condition (2), we also normalize the point A_{n+1} as follows: $A'_{n+1} = \frac{1}{r}A_{n+1}$. Since under this normalization we have

$$(dA'_0, dA'_0) = r^2(dA_0, dA_0),$$

the quadratic form g undergoes the transformation

$$(16) \quad g' = r^2g.$$

Moreover, we have

$$(d^2A'_0, C_n) = r(d^2A_0, C_n),$$

and as a result,

$$(17) \quad h' = rh.$$

It follows from relations (16) and (17) that *the fundamental forms g and h of the hypersurface V^{n-1} are relatively invariant forms of weights 2 and 1, respectively.*

The forms g and h allow us to construct the expression

$$(18) \quad I = \frac{h^2}{g},$$

which is invariant with respect to normalization (15). Hence, this expression is an absolute conformal invariant of the hypersurface V^{n-1} . It is determined in a second differential neighborhood of V^{n-1} . The expression $I = I(x, \omega^i)$ is a homogeneous function of second order with respect to the basic forms ω^i of the hypersurface V^{n-1} . We will call this function the *conformal quadratic element* of the hypersurface V^{n-1} (cf. with the projective linear element of $V^{n-1} \subset P^n$ considered in [6], [7], [8], [10], [1]). At umbilical points, the invariant I vanishes, since $h = 0$ at these points.

Since the invariant I is defined by means of the first and second quadratic fundamental forms the hypersurface V^{n-1} , *it is a second order invariant.*

Lemma. *For $n \geq 4$, at unumbilical points of the hypersurface V^{n-1} , the conformal quadratic element I is not a quadratic form with respect to ω^i .*

Proof. Suppose that

$$\frac{h^2}{g} = \theta,$$

where $\theta = \theta_{ij}\omega^i\omega^j$ is a quadratic form, that is,

$$(19) \quad h^2 = g\theta.$$

Suppose that $\text{rank } h = \rho$. We have $\rho \neq 0$, since the points under consideration are not umbilical. Moreover, we have $\rho \neq 1$, since if $\rho = 1$, then there exists a coordinate system in which all components of the tensor h_{ij} vanish except h_{11} . But then condition (13) reduces to $h_{11}g^{11} = 0$. Since $g^{11} \neq 0$, it follows that $h_{11} = 0$ and $\rho = 0$. Consider the cases $\rho = 2$ and $\rho > 2$ separately. For $\rho = 2$, the form h can be always written as

$$h = \alpha \cdot \beta,$$

where α and β are linear forms with respect to ω^i , since by (13) the form h is alternating. Thus, from equation (19) it follows that the quadratic form g is also decomposable. However, this is impossible since the form g is nondegenerate and for $n \geq 4$, is not decomposable into the product of linear factors.

If $\rho > 2$, then the forms g and h are not decomposable, and hence equation (19) is possible only if g and h are proportional, that is, only at umbilical points. \square

5. Consider two smooth, oriented, connected and simply connected hypersurfaces V^{n-1} and \bar{V}^{n-1} of a conformal space C^n or a pseudoconformal space C_q^n . Suppose that there is a one-to-one correspondence $f : V^{n-1} \rightarrow \bar{V}^{n-1}$ under which $f(x) = \bar{x}$, where $x \in V^{n-1}$ and $\bar{x} \in \bar{V}^{n-1}$. The correspondence f induces a mapping f_* of the tangent bundle $T(V^{n-1})$ onto the tangent bundle $T(\bar{V}^{n-1})$: $f_* : T(V^{n-1}) \rightarrow T(\bar{V}^{n-1})$ such that $f_*|_{V^{n-1}} = f$ and $f_*|_{T_x(V^{n-1})}$ is a linear nondegenerate mapping.

We will prove now the theorem on conformal rigidity of hypersurfaces.

Theorem. *Let $n \geq 4$, and V^{n-1} and \bar{V}^{n-1} be two nonisotropic hypersurfaces without umbilical points in a real conformal space C^n or a real pseudoconformal space C_q^n . Suppose that there is a one-to-one correspondence $f : V^{n-1} \rightarrow \bar{V}^{n-1}$ between points of these hypersurfaces, and in the corresponding points of V^{n-1} and \bar{V}^{n-1} the following condition holds:*

$$(20) \quad \bar{I} = f_*I,$$

where I and \bar{I} are the conformal quadratic elements of the hypersurfaces V^{n-1} and \bar{V}^{n-1} defined above. Then the hypersurfaces V^{n-1} and \bar{V}^{n-1} are conformally equivalent, i.e., there exists a conformal transformation φ of the space C^n or C_q^n such that $\varphi(V^{n-1}) = \bar{V}^{n-1}$.

Proof. Relation (20) can be written in the form

$$(21) \quad \frac{\bar{h}^2}{\bar{g}} = \frac{h^2}{g},$$

from which it follows that

$$g \cdot \bar{h}^2 = \bar{g} \cdot h^2.$$

Here and in what follows, for simplicity, we write g and h instead of f_*g and f_*h . By the above lemma, each pair of the forms \bar{h}^2, \bar{g} and h^2, g do not have common

factors. It follows that

$$(22) \quad \bar{g} = \sigma^2 g, \quad \bar{h} = \sigma h,$$

where $\sigma = \sigma(x) \neq 0$.

Further, let $x \in V^{n-1}$ and $\bar{x} \in \bar{V}^{n-1}$ be two corresponding points of the hypersurfaces V^{n-1} and \bar{V}^{n-1} , and let φ be a conformal transformation mapping $x = A_0$ into $\bar{x} = \bar{A}_0$, the central tangent hypersphere C_n into the central tangent hypersphere \bar{C}_n , and the normal hyperspheres A_i into the normal hyperspheres \bar{A}_i . Then the equations of V^{n-1} and \bar{V}^{n-1} have the form

$$(23) \quad \omega_0^n = 0, \quad \bar{\omega}_0^n = 0.$$

Moreover, the basis forms of V^{n-1} and \bar{V}^{n-1} are equal:

$$(24) \quad \bar{\omega}_0^i = \omega_0^i.$$

Since the first fundamental forms of the hypersurfaces V^{n-1} and \bar{V}^{n-1} have the form

$$g = g_{ij} \omega^i \omega^j, \quad \bar{g} = \bar{g}_{ij} \omega^i \omega^j,$$

and their second fundamental forms have the form

$$h = h_{ij} \omega^i \omega^j, \quad \bar{h} = \bar{h}_{ij} \omega^i \omega^j,$$

where $g^{ij} h_{ij} = 0$ and $\bar{g}^{ij} \bar{h}_{ij} = 0$ (see (13)), it follows that relations (22) are equivalent to the relations

$$(25) \quad \bar{g}_{ij} = \sigma^2 g_{ij}$$

and

$$(26) \quad \bar{h}_{ij} = \sigma h_{ij}.$$

Since $\sigma \neq 0$, then by renormalizing the point A_0 , this factor can be reduced to 1. In fact, setting

$$\bar{A}'_0 = \frac{1}{\sigma} \bar{A}_0,$$

we find that

$$d\bar{A}'_0 = d\left(\frac{1}{\sigma}\right) \bar{A}_0 + \frac{1}{\sigma} (\bar{\omega}_0^0 \bar{A}_0 + \omega^i \bar{A}_i)$$

and

$$(d\bar{A}'_0, d\bar{A}'_0) = \frac{1}{\sigma^2} \bar{g}_{ij} \omega^i \omega^j = g_{ij} \omega^i \omega^j.$$

Thus, we obtained

$$(27) \quad \bar{g}_{ij} = g_{ij}.$$

After the above normalization, we have

$$\bar{h}' = (d^2 \bar{A}'_0, \bar{C}'_n) = \frac{1}{\sigma} (d^2 \bar{A}_0, \bar{C}_n) = \frac{1}{\sigma} \bar{h} = h.$$

It follows that

$$(28) \quad \bar{h}_{ij} = h_{ij}.$$

Note that in (27) and (28) we wrote \bar{g}_{ij} and \bar{h}_{ij} instead of \bar{g}'_{ij} and \bar{h}'_{ij} .

Taking the exterior derivatives of equations (24), we obtain

$$[\bar{\omega}_j^i - \omega_j^i - \delta_j^i (\bar{\omega}_0^0 - \omega_0^0)] \wedge \omega^j = 0.$$

Applying Cartan’s lemma to these equations, we find that

$$(29) \quad \bar{\omega}_j^i - \omega_j^i = \delta_j^i(\bar{\omega}_0^0 - \omega_0^0) + T_{jk}^i \omega^k,$$

where $T_{jk}^i = T_{kj}^i$. It is easy to prove that the quantities T_{jk}^i form a $(1, 2)$ -tensor, which is called the *deformation tensor* of the tangent bundle.

Differentiating equations (27), we obtain

$$g_{ik}(\bar{\omega}_j^k - \omega_j^k) + g_{kj}(\bar{\omega}_i^k - \omega_i^k) = 0.$$

Substituting for $\bar{\omega}_j^i - \omega_j^i$ the values taken from (29), we find that

$$(30) \quad 2g_{ij}(\bar{\omega}_0^0 - \omega_0^0) + (g_{ik}T_{jl}^k + g_{kj}T_{il}^k)\omega^l = 0.$$

It follows that the 1-form $\bar{\omega}_0^0 - \omega_0^0$ is expressed in terms of the basis forms ω^l :

$$(31) \quad \bar{\omega}_0^0 - \omega_0^0 = s_l \omega^l.$$

Next, we make the transformation

$$\bar{A}'_i = \bar{A}_i + x_i \bar{A}_0$$

in the pencil of normal hyperspheres. Since $\bar{A}'_0 = \bar{A}_0$, we have

$$d\bar{A}'_0 = \bar{\omega}_0^0 \bar{A}_0 + \omega^i \bar{A}_i = \bar{\omega}_0^0 \bar{A}_0 + \omega^i (\bar{A}'_i - x_i \bar{A}_0).$$

It follows that

$$'\bar{\omega}_0^0 = \bar{\omega}_0^0 - x_i \omega^i.$$

By (31), from this we find that

$$'\bar{\omega}_0^0 = \omega_0^0 + (s_i - x_i)\omega^i.$$

We can see now that by setting $x_i = s_i$, we reduce relation (31) to the form

$$(32) \quad \bar{\omega}_0^0 = \omega_0^0.$$

By (32), equations (30) take the form

$$g_{il}T_{jk}^l + g_{jl}T_{ik}^l = 0.$$

By cycling these equations with respect to the indices i, j and k and subtracting the first equation from the sum of the last two equations, we obtain the conditions

$$T_{ij}^k = 0,$$

by means of which equations (29) become

$$(33) \quad \bar{\omega}_j^i = \omega_j^i.$$

Taking the exterior derivatives of equations (32), we obtain the exterior quadratic equation

$$(\bar{\omega}_i^0 - \omega_i^0) \wedge \omega^i = 0,$$

from which, by Cartan’s lemma, it follows that

$$(34) \quad \bar{\omega}_i^0 - \omega_i^0 = t_{ij} \omega^j, \quad t_{ij} = t_{ji}.$$

Taking the exterior derivatives of (33), we obtain

$$\omega^i \wedge (\bar{\omega}_j^0 - \omega_j^0) + \bar{\omega}_n^i \wedge \bar{\omega}_j^n - \omega_n^i \wedge \omega_j^n + g^{ik}g_{jl}(\bar{\omega}_k^0 - \omega_k^0) \wedge \omega^l = 0.$$

By (28), the second and third terms on the left-hand side cancel out. Substituting for $\bar{\omega}_i^0 - \omega_i^0$ in the remaining terms the values taken from (34), and using the fact that the forms ω^l are linearly independent, we find that

$$-t_{jk}\delta_l^i + t_{jl}\delta_k^i + g^{im}(t_{mk}g_{jl} - t_{ml}g_{jk}) = 0.$$

Contracting this relation with respect to the indices i and k , we arrive at the equation

$$(35) \quad (n-3)t_{jl} = -tg_{jl},$$

where $t = g^{im}t_{im}$. Since $n \geq 4$, by contracting the latter equation with the tensor g^{jl} , we find that $(2n-4)t = 0$. It follows that $t = 0$, and consequently $t_{jl} = 0$.

As a result, equation (34) takes the form

$$(36) \quad \bar{\omega}_i^0 = \omega_i^0.$$

From equations (14) it follows that

$$(37) \quad \bar{\omega}_i^n = \omega_i^n.$$

Taking the exterior derivatives of equations (37), we obtain

$$(38) \quad \omega_i^{n+1} \wedge (\bar{\omega}_n^0 - \omega_n^0) = 0.$$

By (7), even for $n \geq 3$, the forms ω_i^{n+1} are linearly independent, and as a result, we find that

$$(39) \quad \bar{\omega}_n^0 = \omega_n^0.$$

Exterior differentiation of equations (36) and (39) leads to the identity. Thus the system of equations (23), (24), (27), (32), (33), (36) (37) and (39) is completely integrable.

Moreover, equations (23), (24), (27), (32), (33), (36) (37) and (39) show that all components of an infinitesimal displacement of second order moving frames associated with the hypersurfaces V^{n-1} and \bar{V}^{n-1} coincide. Thus, by the equivalence theorem of É. Cartan (see [3] or [9], the hypersurface \bar{V}^{n-1} can be obtained from the hypersurface V^{n-1} by means of a conformal transformation. Therefore, the hypersurfaces V^{n-1} and \bar{V}^{n-1} are conformally equivalent. \square

As we can see from equation (35), the proof of our main theorem fails if $n = 3$. To prove the rigidity theorem for $n = 3$, it is necessary to add certain additional conditions to condition (20) which are connected with a third order differential neighborhood. Such a theorem for $n = 3$ was proved in [12].

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