

Designation: E 6 - 02a

An American National Standard

# Standard Terminology Relating to Methods of Mechanical Testing<sup>1</sup>

This standard is issued under the fixed designation E 6; the number immediately following the designation indicates the year of original adoption or, in the case of revision, the year of last revision. A number in parentheses indicates the year of last reapproval. A superscript epsilon  $(\epsilon)$  indicates an editorial change since the last revision or reapproval.

This standard has been approved for use by agencies of the Department of Defense.

# 1. Scope

1.1 This terminology covers the principal terms relating to methods of mechanical testing of solids. The general definitions are restricted and interpreted, when necessary, to make them particularly applicable and practicable for use in standards requiring or relating to mechanical tests. These definitions are published to encourage uniformity of terminology in product specifications.

1.2 Terms relating to fatigue and fracture testing are defined in Terminology E 1823.

## 2. Referenced Documents

2.1 ASTM Standards:

E 8 Test Methods for Tension Testing of Metallic Materials<sup>2</sup> E 8M Test Methods for Tension Testing of Metallic Materials [Metric]<sup>2</sup>

E 796 Test Method for Ductility Testing of Metallic Foil<sup>2</sup> E 1823 Terminology Relating to Fatigue and Fracture Testing<sup>2</sup>

# 3. Index of Terms

3.1 The definitions of the following terms, which are listed alphabetically, appear in the indicated sections of 4.1.

Term	Section
angle of bend	D
angle of twist	В
angular strain	see <b>strain</b>
axial strain	see strain
bearing area	F
bearing force	F
bearing strain	F
bearing strength	F
bearing stress	F
bearing yield strength	F
bend test	D
break elongation	see maximum elongation
breaking load	В

<sup>&</sup>lt;sup>1</sup> This terminology is under the jurisdiction of ASTM Committee E28 on Mechanical Testing and is the direct responsibility of Subcommittee E28.91 on Editorial and Terminology except where designated otherwise. A subcommittee designation in parentheses following a definition indicates the subcommittee with responsibility for that definition.

Brinell hardness number Brinell hardness test	C C
calibration	G
calibration factor	G
chord modulus	see modulus of elasticity
compressive strength	В
compressive stress	see stress
compressometer	G
constraint	Α
creep	E
creep recovery	E
creep rupture strength	Е
creep strength	E
deflectometer	G
discontinuous yielding	В
ductility	A
edge distance	F
edge distance ratio	F
elastic constants	see modulus of elasticity and Poisson's
olabilo conotanto	ratio
elastic limit	A
elastic true strain	A
elongation	В
engineering strain	see <b>strain</b>
engineering strain	see stress
extensometer	G
	G
extensometer system	В
fatigue ductility fatigue ductility exponent	В
fatigue life	В
fracture ductility	A
,	A
fracture strength	
fracture stress	see stress
free bend	D A
force	
gage length	G
guided bend	D
hardness	С
indentation hardness	C
initial recovery	E E
initial strain	<del>-</del>
initial stress	E
Knoop hardness number	С
Knoop hardness test	C
linear (tensile or compressive) strain	see <b>strain</b>
load	A
lower yield strength	В
macrostrain	see strain
malleability	see ductility
mandrel (in bend testing)	D
maximum elongation	В
mechanical hysteresis	A
mechanical properties	A
machanical tacting	۸

see strain

see modulus of elasticity

mechanical testing

modulus of elasticity

modulus of rigidity

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<sup>&</sup>lt;sup>2</sup> Annual Book of ASTM Standards, Vol 03.01.



modulus of rupture in bending	D
modulus of rupture in torsion	В
necking	В
nominal stress	see stress
normal stress	see stress
physical properties	see mechanical properties
pin	see mandrel (in bend testing)
plastic true strain	Α Α
plunger	see mandrel (in bend testing)
principal stress	see stress
Poisson's ratio	A
proportional limit	A
radius of bend	D
rate of creep	E
reduction of area	В
relaxation rate	E
relaxed stress	Ē
	E
remaining stress residual strain	<del>=</del>
	see strain
residual stress	see stress
Rockwell hardness number	C
Rockwell hardness test	C
Rockwell superficial hardness num-	see Rockwell hardness number
ber	0
Rockwell superficial hardness test	C D
semi-guided bend	<del>-</del>
Scleroscope hardness number	С
Scleroscope hardness test	C
set	A
secant modulus shear fracture	see modulus of elasticity
shear modulus	В А
shear strain	see <b>strain</b>
shear strength	B
shear stress	see <b>stress</b> B
slenderness ratio	<del>-</del>
static fatigue strength strain	see <b>creep rupture strength</b> A
strain gage fatigue life	see fatigue life
stress	A
stress relaxation	Ē
stress-rupture strength	see creep rupture strength
stress-strain diagram	A
tangent modulus	see modulus of elasticity
tensile strength	B
tensile stress	see stress
torque	A
torsional modulus	see modulus of elasticity
torsional stress	see stress
total elongation	В
transverse strain	see <b>strain</b>
true strain	see <b>strain</b>
true stress	see strain
ultimate elongation	see maximum elongation
uniform elongation	В
upper yield strength	В
verification	G
Vickers hardness number	C
Vickers hardness test	C
wrap-around bend	D
yield point	В
yield point elongation	В
yield strength	В
Young's modulus	A
zero time	Ē
	-

# 4. Terminology

## 4.1 Terms and Definitions:

## A. GENERAL DEFINITIONS

**constraint,** n—any restriction to the deformation of a body. (E28.11)

**ductility,** *n*—the ability of a material to deform plastically before fracturing. (**E28.02**)

Discussion—Ductility is usually evaluated by measuring (1) the

elongation or reduction of area from a tension test, (2) the depth of cup from a cupping test, (3) the radius or angle of bend from the bend test, or (4) the fatigue ductility from the fatigue ductility test (see Test Method E 796).

Discussion—Malleability is the ability to deform plastically under repetitive compressive forces.

**elastic limit** [FL<sup>-2</sup>], n—the greatest stress which a material is capable of sustaining without any permanent strain remaining upon complete release of the stress.

DISCUSSION—Due to practical considerations in determining the elastic limit, measurements of strain, using a small force rather than zero force, are usually taken as the initial and final reference.

**fracture ductility,**  $\epsilon_f$ , n—the true plastic strain at fracture. **fracture strength,**  $S_f$  [FL<sup>-2</sup>], n—the normal stress at the beginning of fracture. Fracture strength is calculated from the force at the beginning of fracture during a tension test and the original cross-sectional area of the specimen.

**force** [F], *n*—in mechanical testing, a vector quantity of fundamental nature characterized by a magnitude, a direction, a sense, and a discrete point of application, that acts externally upon a test object and creates stresses in it. **(E28.91)** 

Discussion—Force is a derived unit of the SI system. Units of force in the SI system are newtons (N).

DISCUSSION—Where applicable, the noun **force** is preferred to **load** in terminology for mechanical testing.

**least count,** *n*—the smallest change in indication that can customarily be determined and reported.

DISCUSSION—In machines with close graduations it may be the value of a graduation interval; with open graduations or with magnifiers for reading, it may be an estimated fraction, rarely as fine as one tenth, of a graduated interval; and with verniers it is customarily the difference between the scale and vernier graduation measured in terms of scale units. If the indicating mechanism includes a stepped detent, the detent action may determine the least count.

**load** [F], *n*—in mechanical testing, an external force or system of forces or pressures, or both, that act upon the test object. (E28.91)

Discussion—**Load** is a deprecated term and, where applicable, it should be replaced by **force**, particularly where it is used as a noun. For reasons of editorial simplicity or traditional usage, replacement of **load** by **force** may not always be desirable when used as a verb, adjective, or other part of speech (for example, to load a specimen, loading rate, load cell).

**mechanical hysteresis**, *n*—the energy absorbed in a complete cycle of loading and unloading. **(E28.03)** 

DISCUSSION—A complete cycle of loading and unloading includes any stress cycle regardless of the mean stress or range of stress.

**mechanical properties,** *n*—those properties of a material that are associated with elastic and inelastic reaction when force is applied, or that involve the relationship between stress and strain.

Discussion—These properties have often been referred to as "physical properties," but the term "mechanical properties" is much to be preferred.

**mechanical testing,** *n*—the determination of mechanical properties. **(E28.90)** 



**modulus of elasticity**  $[FL^{-2}]$ , n—the ratio of stress to corresponding strain below the proportional limit.

Discussion—The stress-strain relations of many materials do not conform to Hooke's law throughout the elastic range, but deviate therefrom even at stresses well below the elastic limit. For such materials the slope of either the tangent to the stress-strain curve at the origin or at a low stress, the secant drawn from the origin to any specified point on the stress-strain curve, or the chord connecting any two specified points on the stress-strain curve is usually taken to be the "modulus of elasticity." In these cases the modulus should be designated as the "tangent modulus," the" secant modulus," or the "chord modulus," and the point or points on the stress-strain curve described. Thus, for materials where the stress-strain relationship is curvilinear rather than linear, one of the four following terms may be used:

- (a) initial tangent modulus  $[FL^{-2}]$ , n—the slope of the stress-strain curve at the origin.
- (b) tangent modulus [FL<sup>-2</sup>], n—the slope of the stress-strain curve at any specified stress or strain.
- (c) secant modulus [FL<sup>-2</sup>], n—the slope of the secant drawn from the origin to any specified point on the stress-strain curve.
- (d) chord modulus [FL<sup>-2</sup>], n—the slope of the chord drawn between any two specified points on the stress-strain curve.

DISCUSSION—Modulus of elasticity, like stress, is expressed in force per unit of area (pounds per square inch, etc.).

**Poisson's ratio**, μ, *n*—the absolute value of the ratio of transverse strain to the corresponding axial strain resulting from uniformly distributed axial stress below the proportional limit of the material. (**E28.03**)

Discussion—Above the proportional limit, the ratio of transverse strain to axial strain will depend on the average stress and on the stress range for which it is measured and, hence should not be regarded as Poisson's ratio. If this ratio is reported, nevertheless, as a value of "Poisson's ratio" for stresses beyond the proportional limit, the range of stress should be stated.

Discussion—Poisson's ratio will have more than one value if the material is not isotropic.

**proportional limit**  $[FL^{-2}]$ , n—the greatest stress which a material is capable of sustaining without any deviation from proportionality of stress to strain (Hooke's law).

DISCUSSION—Many experiments have shown that values observed for the proportional limit vary greatly with the sensitivity and accuracy of the testing equipment, eccentricity of loading, the scale to which the stress-strain diagram is plotted, and other factors. When determination of proportional limit is required, the procedure and the sensitivity of the test equipment should be specified.

**set**—strain remaining after complete release of the force producing the deformation.

DISCUSSION—Due to practical considerations, such as distortion in the specimen and slack in the strain indicating system, measurements of strain at a small force rather than zero force are often taken.

Discussion—Set is often referred to as permanent set if it shows no further change with time. Time elapsing between removal of force and final reading of set should be stated.

**shear modulus,** G [FL<sup>-2</sup>], n—the ratio of shear stress to corresponding shear strain below the proportional limit of the material. (E28.03)

Discussion—The value of the shear modulus may depend on the direction in which it is measured if the material is not isotropic. Wood, many plastics and certain metals are markedly anisotropic. Deviations from isotropy should be suspected if the shear modulus differs from that

determined by substituting independently measured values of Young's modulus, *E*, and Poisson's ratio,  $\mu$ , in the relation:

$$G = E/[2(1 + \mu)]$$

Discussion—In general, it is advisable in reporting values of shear modulus to state the range of stress over which it is measured.

**strain**, *e*, *n*—the per unit change, due to force, in the size or shape of a body referred to its original size or shape. Strain is a nondimensional quantity, but it is frequently expressed in inches per inch, metres per metre, or percent.

DISCUSSION—In this standard, "original" refers to dimensions or shape of cross section of specimens at the beginning of testing.

Discussion—Strain at a point is defined by six components of strain: three linear components and three shear components referred to a set of coordinate axes.

Discussion—In the usual tension, compression, or torsion test it is customary to measure only one component of strain and to refer to this as "the strain." In a tension or a compression test this is usually the axial component.

Discussion—Strain has an elastic and a plastic component. For small strains the plastic component can be imperceptibly small.

Discussion—Linear thermal expansion, sometimes called "thermal strain," and changes due to the effect of moisture are not to be considered strain in mechanical testing.

angular strain, n—use shear strain.

axial strain, n—linear strain in a plane parallel to the longitudinal axis of the specimen. (E28.04)

elastic true strain,  $\epsilon_{\rm e}$ , n—elastic component of the true strain. engineering strain, e, n—a dimensionless value that is the change in length ( $\Delta L$ ) per unit length of original linear dimension ( $L_0$ ) along the loading axis of the specimen; that is,  $e = (\Delta L)/L_0$ . (E28.02)

linear (tensile or compressive) strain, n—the change per unit length due to force in an original linear dimension. (E28.04)

Discussion—An increase in length is considered positive.

macrostrain, n—the mean strain over any finite gage length of measurement large in comparison with interatomic distances. (E28.13)

Discussion—Macrostrain can be measured by several methods, including electrical-resistance strain gages and mechanical or optical extensometers. Elastic macrostrain can be measured by X-ray diffraction

DISCUSSION—When either of the terms *macrostrain* or *microstrain* is first used in a document, it is recommended that the physical dimension or the gage length, which indicate the size of the reference strain volume involved, be stated.

*microstrain*, *n*—the strain over a gage length comparable to interatomic distances. (E28.13)

Discussion—These are the strains being averaged by the macrostrain measurement. Microstrain is not measurable by existing techniques. Variance of the microstrain distribution can, however, be measured by X-ray diffraction.

Discussion—When either of the terms *macrostrain* or *microstrain* is first used in a document, it is recommended that the physical dimension or the gage length, which indicate the size of the reference strain volume involved, be stated.

plastic true strain,  $\epsilon_{\mathbf{p}}$ , n—the inelastic component of true strain.



residual strain, n—strain associated with residual stress. (E28.13)

DISCUSSION—Residual strains are elastic.

shear strain, n—the tangent of the angular change, due to force, between two lines originally perpendicular to each other through a point in a body. (E28.04)

transverse strain, n—linear strain in a plane perpendicular to the axis of the specimen.

Discussion—Transverse strain may differ with direction in anisotropic materials.

true strain,  $\epsilon$ , n—the natural logarithm of the ratio of instantaneous gage length, L, to the original gage length,  $L_0$ ; that is,  $\epsilon = \ln (L/L_0)$  or  $\epsilon = \ln (1+e)$ . (E28.02)

stress [FL<sup>-2</sup>], *n*—the intensity at a point in a body of the forces or components of force that act on a given plane through the point. Stress is expressed in force per unit of area (poundsforce per square inch, megapascals, and so forth).

DISCUSSION—As used in tension, compression, or shear tests prescribed in product specifications, stress is calculated on the basis of the original dimensions of the cross section of the specimen. This stress is sometimes called "engineering stress," to emphasize the difference from true stress.

compressive stress [FL<sup>-2</sup>], n—normal stress due to forces directed toward the plane on which they act. (E28.04)

engineering stress, S [ $FL^{-2}$ ], n—the normal stress, expressed in units of applied force, F, per unit of original cross-sectional area,  $A_0$ ; that is,  $S = F/A_0$ . (E28.02)

fracture stress  $[FL^{-2}]$ , n—the true normal stress on the minimum cross-sectional area at the beginning of fracture.

Discussion—This term usually applies to tension tests of unnotched specimens.

nominal stress [FL<sup>-2</sup>], n—the stress at a point calculated on the net cross section by simple elastic theory without taking into account the effect on the stress produced by geometric discontinuities such as holes, grooves, fillets, and so forth.

normal stress  $[FL^{-2}]$ , n—the stress component perpendicular to a plane on which the forces act.

principal stress (normal) [FL<sup>-2</sup>], n—the maximum or minimum value of the normal stress at a point in a plane considered with respect to all possible orientations of the considered plane. On such principal planes the shear stress is zero.

DISCUSSION—There are three principal stresses on three mutually perpendicular planes. The states of stress at a point may be:

- (1) uniaxial  $[FL^{-2}]$ , n—a state of stress in which two of the three principal stresses are zero,
- (2) biaxial [FL<sup>-2</sup>], n—a state of stress in which only one of the three principal stresses is zero, or
- (3) triaxial [FL $^{-2}$ ], n—a state of stress in which none of the principal stresses is zero.
  - (4) multiaxial  $[FL^{-2}]$ , n—biaxial or triaxial.

residual stress [FL<sup>-2</sup>], n—stress in a body which is at rest and in equilibrium and at uniform temperature in the absence of external and mass forces. (E28.13)

shear stress [FL $^{-2}$ ], n—the stress component tangential to the plane on which the forces act. (E28.04)

tensile stress [FL<sup>-2</sup>], n—normal stress due to forces directed away from the plane on which they act. (E28.04) torsional stress [FL<sup>-2</sup>], n—the shear stress in a body, in a plane normal to the axis of rotation, resulting from the application

true stress,  $\sigma$  [FL<sup>-2</sup>], n—the instantaneous normal stress, calculated on the basis of the instantaneous cross-sectional area, A; that is,  $\sigma = F/A$ ; if no necking has occurred,  $\sigma = S(1+e)$ . (E28.02)

stress-strain diagram, *n*—a diagram in which corresponding values of stress and strain are plotted against each other. Values of stress are usually plotted as ordinates (vertically) and values of strain as abscissas (horizontally). (E28.04)

**torque** [FL] , *n*—a moment (of forces) that produces or tends to produce rotation or torsion. **(E28.03)** 

**Young's modulus,** E [FL<sup>-2</sup>], n—modulus of elasticity in tension or compression.

# B. TENSION, COMPRESSION, DUCTILITY, SHEAR, AND TORSION TESTING

**angle of twist (torsion test),** *n*—the angle of relative rotation measured in a plane normal to the torsion specimen's longitudinal axis over the gage length. **(E28.03)** 

**breaking force**[F], n—the force at which fracture occurs. (E28.04)

DISCUSSION—When used in connection with tension tests of thin materials or materials of small diameter for which it is often difficult to distinguish between the breaking force and the maximum force developed, the latter is considered to be the breaking force.

compressive strength [FL<sup>-2</sup>], *n*—the maximum compressive stress which a material is capable of sustaining. Compressive strength is calculated from the maximum force during a compression test and the original cross-sectional area of the specimen. (E28.04)

Discussion—In the case of a material which fails in compression by a shattering fracture, the compressive strength has a very definite value. In the case of materials which do not fail in compression by a shattering fracture, the value obtained for compressive strength is an arbitrary value depending upon the degree of distortion which is regarded as indicating complete failure of the material.

**discontinuous yielding,** *n*—a hesitation or fluctuation of force observed at the onset of plastic deformation, due to localized yielding. **(E28.04)** 

Discussion—The stress-strain curve need not appear to be discontinuous.

**elongation,** *El*, *n*—the increase in gage length of a body subjected to a tension force, referenced to a gage length on the body. Usually elongation is expressed as a percentage of the original gage length. **(E28.04)** 

Discussion—The increase in gage length may be determined either *at* or *after* fracture, as specified for the material under test.

Discussion—The term elongation, when applied to metals, generally means measurement after fracture; when applied to plastics and elastomers, measurement at fracture. Such interpretation is usually applicable to values of elongation reported in the literature when no further qualification is given.

Discussion—In reporting values of elongation the gage length shall be stated.

DISCUSSION—Elongation is affected by: specimen geometry; length, width, thickness of the gage section and adjacent regions; and test procedure, such as alignment and speed of pulling.

**fatigue ductility,**  $D_{\mathbf{f}}$ —the ability of a material to deform plastically before fracturing, determined from a constant-strain amplitude, low-cycle fatigue test. (E28.04)

Discussion—Fatigue ductility is usually expressed in percent in direct analogy with elongation and reduction of area ductility measures.

DISCUSSION—The fatigue ductility corresponds to the fracture ductility. Elongation and reduction of area represent the engineering tensile strain after fracture.

Discussion—For the purpose of this definition, the fatigue ductility exponent, c, is defined as c=-0.60.

DISCUSSION—The fatigue ductility is used for metallic foil for which the tension test does not give useful elongation and reduction of area measures

**fatigue ductility exponent,** c, n—the slope of a log-log plot of the plastic strain range and the fatigue life. **(E28.04)** 

**fatigue life,**  $N_{\mathbf{f}}$ , n—the numbers of cycles of stress or strain of a specified character that a given specimen sustains before failure of a specified nature occurs. (**E28.04**)

strain gage fatigue life, n—the number of fully reversed strain cycles corresponding to the onset of degraded gage performance, whether due to excessive zero shift or other detectable failure mode. (E28.14)

**lower yield strength,** LYS [FL<sup>-2</sup>], *n*—the minimum stress recorded during discontinuous yielding, ignoring transient effects. See Figs. 1 and 2. (E28.04)

**maximum elongation,**  $El_{max}$ , n—the elongation at the time of fracture, including both elastic and plastic deformation of the tensile specimen. (**E28.04**)

Discussion—This definition is used for rubber, plastic, and some metallic materials.

Discussion—Maximum elongation is also called ultimate elongation or break elongation.

**modulus of rupture in torsion** [FL $^{-2}$ ], n—the value of maximum shear stress in the extreme fiber of a member of circular cross section loaded to failure in torsion computed from the equation:

$$S_{s} = Tr/J \tag{1}$$

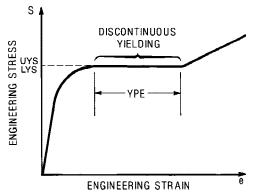


FIG. 1 Stress-Strain Diagram for Determination of Upper and Lower Yield Strengths and Yield Point Elongation in a Material Exhibiting Discontinuous Yielding

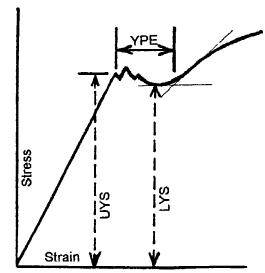


FIG. 2 Stress Strain Diagram Showing Yield Point Elongation and Upper and Lower Yield Strengths

where:

T = maximum twisting moment,

r = original outer radius, and

J = polar moment of inertia of the original cross section.

(E28.04)

Discussion—When the proportional limit in shear is exceeded, the modulus of rupture in torsion is greater than the actual maximum shear stress in the extreme fiber, exclusive of the effect of stress concentration near points of application of torque.

Discussion—If the criterion for failure is other than fracture or attaining the first maximum of twisting moment, it should be so stated.

**necking,** n—the onset of nonuniform or localized plastic deformation, resulting in a localized reduction of cross-sectional area. (**E28.02**)

reduction of area, n—the difference between the original cross-sectional area of a tension test specimen and the area of its smallest cross section. The reduction of area is usually expressed as a percentage of the original cross-sectional area of the specimen. (E28.04)

Discussion—The smallest cross section may be measured at or after fracture as specified for the material under test.

DISCUSSION—The term reduction of area when applied to metals generally means measurement after fracture; when applied to plastics and elastomers, measurement at fracture. Such interpretation is usually applicable to values for reduction of area reported in the literature when no further qualification is given.

**shear fracture,** *n*—a mode of fracture in crystalline materials resulting from translation along slip planes which are preferentially oriented in the direction of the shearing stress.

**shear strength**  $[FL^{-2}]$ , n—the maximum shear stress which a material is capable of sustaining. Shear strength is calculated from the maximum force during a shear or torsion test and is based on the original dimensions of the cross section of the specimen. **(E28.04)** 

**slenderness ratio,** *n*—the effective unsupported length of a uniform column divided by the least radius of gyration of the cross-sectional area. **(E28.04)** 

**tensile strength,**  $S_u$  [FL<sup>-2</sup>], n—the maximum tensile stress which a material is capable of sustaining. Tensile strength is calculated from the maximum force during a tension test carried to rupture and the original cross-sectional area of the specimen. (E28.04)

**total elongation,**  $El_t$ , n—the elongation determined after fracture by realigning and fitting together of the broken ends of the specimen. (E28.04)

Discussion—This definition is usually used for metallic materials.

uniform elongation,  $El_u[\%]$ , n—the elongation determined at the maximum force sustained by the test piece just prior to necking, or fracture, or both. (E28.04)

Discussion—Uniform elongation includes both elastic and plastic elongation.

**upper yield strength,** UYS [FL<sup>-2</sup>], n—the first stress maximum (stress at first zero slope) associated with discontinuous yielding. See Figs. 1 and 2, and Fig. 3 (E28.04)

yield point, YP [FL<sup>-2</sup>], n—term previously used, by E 8 and E 8M, for the property which is now referred to as upper yield strength. (E28.04)

yield point elongation, YPE, n—the strain (expressed in percent) separating the stress-strain curve's first point of zero slope from the point of transition from discontinuous yielding to uniform strain hardening. (E28.04)

DISCUSSION—If the transition occurs over a range of strain, the YPE end point is the intersection between (a) a horizontal line tangent to the curve at the last zero slope and (b) a line drawn tangent to the strain hardening portion of the stress-strain curve at the point of inflection. If there is no point at or near the onset of yielding at which the slope reaches zero, the material has 0% YPE.

**yield strength,** YS or  $S_y$  [FL<sup>-2</sup>], n—the engineering stress at which, by convention, it is considered that plastic elongation of the material has commenced. This stress may be specified in terms of (a) a specified deviation from a linear stress-strain relationship, (b) a specified total extension attained, or (c) maximum or minimum engineering stresses measured during discontinuous yielding. (**E28.04**)

Discussion—The following types of yield strengths, which correspond to the approaches listed above may be specified:
(a) specified offset yield strength, n (usually an offset strain of 0.2 % is

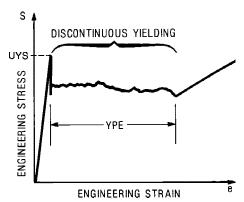


FIG. 3 Stress-Strain Diagram for Determination of Upper Yield Strength and Yield Point Elongation in a Material Exhibiting Discontinuous Yielding

specified)—the engineering stress at which the material has been plastically strained by an amount equal to the specified offset strain. This stress is reached at the point where the stress-strain curve intersects a line having a slope equal to the modulus of elasticity and constructed such that it is offset from the linear portion of the stress-strain curve by an amount equal to the specified strain (see Fig. 4)

(b) specified extension under load yield strength, n (usually a strain of 0.5 % is specified, although higher strains may need to be used in testing of elastomers, polymers, and high-strength materials, to ensure that the yield strength determined will exceed the material's elastic limit)—the engineering stress at which the material has elongated (including both elastic and plastic deformation) an amount corresponding to the specified strain. This stress is attained at the point where the stress-strain curve intersects a line drawn parallel to the stress axis at the specified strain on the strain axis (see Fig. 5).

(c) upper or lower yield strengths, n—the upper (first maximum) or the lower (minimum, ignoring transient effects) engineering stress measured during discontinuous yielding occurring at or near the onset of plastic deformation (see Figs. 1 and 2, and Fig. 3).

DISCUSSION—When yield strength is specified, the type of yield strength must be stated, along with the specified offset or extension under load, when applicable. The following are examples: YS (0.2 % offset), YS (0.5 % EUL), UYS, LYS.

Discussion—Offset or extension under load yield strengths should be specified for continuously yielding materials, because upper and lower yield strengths are not defined for such materials. Determination of upper or lower yield strengths, or both, is often favored for discontinuously yielding materials, because offsets or extensions constructed would generally intersect the portion of the stress-strain curve reflecting the stress oscillations which are characteristic of discontinuous yielding.

DISCUSSION—The values obtained by the methods described above may differ. However, when discontinuous yielding causes the stress-strain curve to show a stress hesitation with no pronounced increases or decreases (see Fig. 1), the offset, *EUL* and upper and lower yield strengths generally approach or attain a common value.

Discussion—Yield strength, however determined, is generally affected by speed of testing. However, upper and lower yield strengths can also be dramatically influenced by test equipment parameters such as stiffness and alignment. (For more information, consult Appendix 1 of E 8 or E 8M.)

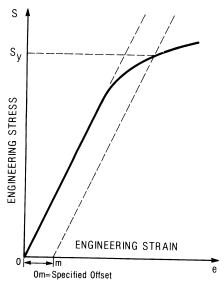


FIG. 4 Stress-Strain Diagram for Determination of Yield Strength by the Offset Method

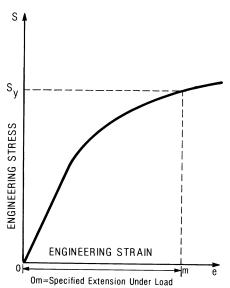


FIG. 5 Stress-Strain Diagram for Determination of Yield Strength by the Extension-Under-Load Method

#### C. HARDNESS TESTING

**Brinell hardness number,** HB , *n*—a number related to the applied force and to the surface area of the permanent impression made by a ball indenter computed from the equation:

$$HB = 2P/\beta D(D - \sqrt{D^2 - d^2})$$
 (2)

where:

P = applied force, kgf,

D = diameter of ball, mm, and

d = mean diameter of the impression, mm.

(E28.06)

Discussion—The Brinell hardness number followed by the symbol HB without any suffix numbers denotes the following test conditions:

Ball diameter 10 mm
Force 3000 kgf
Duration of loading 10 to 15 s

For other conditions, the hardness number and symbol HB is supplemented by numbers indicating the test conditions in the following order: diameter of ball, force, and duration of loading.

**Brinell hardness test,** *n*—an indentation hardness test using calibrated machines to force a hard ball, under specified conditions, into the surface of the material under test and to measure the diameter of the resulting impression after removal of the force. **(E28.06)** 

**hardness,** *n*—the resistance of a material to deformation, particularly permanent deformation, indentation, or scratching. **(E28.06)** 

DISCUSSION—Different methods of evaluating hardness give different ratings because they are measuring somewhat different quantities and characteristics of the material. There is no absolute scale for hardness; therefore, to express hardness quantitatively, each type of test has its own scale of arbitrarily defined hardness.

**indentation hardness,** *n*—the hardness as evaluated from measurements of area or depth of the indentation made by pressing a specified indenter into the surface of a material under specified static loading conditions. (**E28.06**)

**Knoop hardness number,** HK, *n*—a number related to the applied force and to the projected area of the permanent impression made by a rhombic-based pyramidal diamond indenter having included edge angles of 172° 30 min and 130° 0 min computed from the equation:

$$HK = P/0.07028d^2 \tag{3}$$

where:

P = applied force, kgf, and

d = long diagonal of the impression, mm.

In reporting Knoop hardness numbers, the test force is stated. (E28.06)

**Knoop hardness test,** *n*—an indentation hardness test using calibrated machines to force a rhombic-based pyramidal diamond indenter having specified edge angles, under specified conditions, into the surface of the material under test and to measure the long diagonal after removal of the force.

(E28.06)

**Rockwell hardness number,** HR, n—a number derived from the net increase in the depth of indentation as the force on an indenter is increased from a specified preliminary test force to a specified total test force and then returned to the preliminary test force. (**E28.06**)

Discussion—Indenters for the Rockwell hardness test include a diamond sphero-conical indenter and steel ball indenters of several specified diameters.

Discussion—Rockwell hardness numbers are always quoted with a scale symbol representing the indenter and forces used. The hardness number is followed by the symbol HR and the scale designation. Examples:

64 HRC = Rockwell hardness number of 64 on Rockwell C Scale. 81 HR 30N = Rockwell superficial hardness number of 81 on Rockwell 30N scale.

**Rockwell hardness test,** *n*—an indentation hardness test using a verified machine to force a diamond sphero-conical indenter (diamond indenter) or a hard steel ball indenter, under specified conditions into the surface of the material under test in two operations, and to measure the difference in depth of the indentation under the specified conditions of preliminary and total test forces (minor and major loads, respectively). **(E28.06)** 

**Rockwell superficial hardness test,** *n*—same as the Rockwell hardness test except that smaller preliminary and total test forces are used. **(E28.06)** 

Scleroscope hardness number, HSc or HSd, , *n*—a number related to the height of rebound of a diamond-tipped hammer dropped on the material being tested. (E28.06)

Discussion—It is measured on a scale determined by dividing into 100 units the average rebound of the hammer from a quenched (to maximum hardness) and untempered high carbon water-hardening tool steel test block of AISI W-5.

Scleroscope hardness test, *n*—a dynamic indentation hardness test using a calibrated instrument that drops a diamond-tipped hammer from a fixed height onto the surface of the material under test. (E28.06)

Discussion—The height of rebound of the hammer is a measure of the hardness of the material.

**Vickers hardness number,** HV , n—a number related to the

applied force and the surface area of the permanent impression made by a square-based pyramidal diamond indenter having included face angles of 136°, computed from the equation:

$$HV = 2P \sin (\alpha/2)/d^2 = 1.8544P/d^2$$
 (4)

where:

P = applied force, kgf,

d = mean diagonal of the impression, mm, and

 $\alpha$  = face angle of diamond = 136°.

(E28.06)

DISCUSSION—The Vickers pyramid hardness number is followed by the symbol HV with a suffix number denoting the force and a second suffix number indicating the duration of loading when the latter differs from the normal loading time, which is 10 to 15 s.

**Vickers hardness test,** *n*—an indentation hardness test using calibrated machines to force a square-based pyramidal diamond indenter having specified face angles, under a predetermined force, into the surface of the material under test and to measure the diagonals of the resulting impression after removal of the force. **(E28.06)** 

#### D. BEND TESTING

**angle of bend,** *n*—the change in the angle between the two legs of the specimen during a bend test, measured before release of the bending forces. (**E28.02**)

Discussion—The angle of bend is measured before release of the bending force, unless otherwise specified.

**bend test,** *n*—a test for ductility performed by bending or folding a specimen, usually by steadily applied forces but in some instances by blows. The bending may be interrupted to examine the bent surface for cracks. **(E28.02)** 

DISCUSSION—The ductility is usually judged by whether or not the specimen cracks under the specified conditions of the test.

DISCUSSION—There are four general types of bend tests according to the manner in which the forces are applied to the specimen to make the bend. These are as follows:

- 1. Free Bend
- 2. Guided Bend
- 3. Semi-Guided Bend
- 4. Wrap-Around Bend

Discussion—The specimen has a substantially uniform cross-section and a length several times as great as the largest dimension of the cross-section.

free bend, n—the bend obtained by applying forces to the ends of a specimen without the application of force at the point of maximum bending. (E28.02)

Discussion—In making a free bend, lateral forces first are applied to produce a small amount of bending at two points. The two bends, each a suitable distance from the center, are both in the same direction.

**guided bend,** *n*—the bend obtained by using a mandrel to guide and force the portion of the specimen being bent between two faces of a die. (E28.02)

mandrel (in bend testing), *n*—the tool used to control the strain on the concave side of a bend in a wrap-around bend test and also to apply the bending force in a semi-guided or guided bend test. (E28.02)

Discussion—The terms "pin" and "plunger" have been used in place of mandrel

Discussion—In free bends or semi-guided bends to an angle of  $180^{\circ}$  a shim or block of the proper thickness may be placed between the legs of the specimen as bending is completed. This shim or block is also referred to as a pin or mandrel.

**modulus of rupture in bending** [FL $^{-2}$ ], n—the value of maximum tensile or compressive stress (whichever causes failure) in the extreme fiber of a beam loaded to failure in bending computed from the flexure equation:

$$S_b = Mc/I \tag{5}$$

where:

M =maximum bending moment, computed from the maximum force and the original moment arm,

c = initial distance from the neutral axis to the extreme fiber where failure occurs, and

I = initial moment of inertia of the cross section about the neutral axis.

(E28.02)

Discussion—When the proportional limit in either tension or compression is exceeded, the modulus of rupture in bending is greater than the actual maximum tensile or compressive stress in the extreme fiber, exclusive of the effect of stress concentration near points of force application.

Discussion—If the criterion for failure is other than rupture or attaining the first maximum force, it should be so stated.

radius of bend, n—the radius of the cylindrical surface of the pin or mandrel that comes in contact with the inside surface of the bend during bending. In the case of free or semiguided bends to 180° in which a shim or block is used, the radius of bend is one half the thickness of the shim or block.

(E28.02)

**semi-guided bend,** n—the bend obtained by applying a force directly to the specimen in the portion that is to be bent. (E28.02)

DISCUSSION—The specimen is either held at one end or forced around a pin or rounded edge, or is supported near the ends and bent by a force applied on the side of the specimen opposite the supports and midway between them. In some instances, the bend is started in this manner and finished in the manner of the free bend.

**wrap-around bend**, *n*—the bend obtained when a specimen is wrapped in a closed helix around a cylindrical mandrel. **(E28.02)** 

Discussion—This term is sometimes applied to a semi-guided bend of  $180^{\circ}$  or less.

# E. CREEP AND STRESS-RELAXATION TESTING

**creep,** *n*—the time-dependent increase in strain in a solid resulting from force. (**E28.10**)

DISCUSSION—Creep tests are usually made at constant load and at constant temperature. For tests on plastics the initial strain, however defined, is included and for metals it is not.

Discussion—This change in strain is sometimes referred to as creep strain.

**creep recovery**, *n*—the time-dependent decrease in strain in a solid, following the removal of force. **(E28.10)** 

Discussion—Recovery is usually determined at constant temperature.



Discussion—In tests of plastics, the initial recovery is generally included; for metals it is not. Thermal expansion is excluded.

**creep rupture strength** [FL $^{-2}$ ], n—the stress that will cause fracture in a creep test at a given time, in a specified constant environment. **(E28.10)** 

Discussion—This is sometimes referred to as the *stress-rupture strength*. In glass technology this is termed the "static fatigue strength."

**creep strength** [FL $^{-2}$ ], n—the stress that causes a given creep in a creep test at a given time in a specified constant environment. (E28.10)

**initial recovery,** *n*—the decrease in strain in a specimen resulting from the removal of force, before creep recovery takes place. **(E28.10)** 

Discussion—This is sometimes referred to as instantaneous recovery. Discussion—Recovery is usually determined at constant temperature. Thermal expansion is excluded.

DISCUSSION—For tests on plastics, the initial recovery is generally included as part of creep recovery.

DISCUSSION—This definition describes a quantity which is difficult to measure accurately. The values obtained may vary greatly with the sensitivity and accuracy of the test equipment. When determining this quantity, the procedure and characteristics of the test equipment should be reported.

**initial strain,** *n*—the strain introduced into a specimen by the given loading conditions, before creep takes place. (**E28.10**)

Discussion—This is sometimes referred to as instantaneous strain.

**initial stress,** *n*—the stress introduced into a specimen by imposing the given constraint conditions before stress relaxation takes place. **(E28.11)** 

Discussion—This is sometimes referred to as instantaneous stress.

rate of creep, *n*—the slope of the creep-time curve at a given time. (E28.10)

**relaxation rate,** *n*—the absolute value of the slope of the relaxation curve at a given time. **(E28.11)** 

Discussion—A relaxation curve is a plot of either the remaining or relaxed stress as a function of time.

relaxed stress, *n*—the initial stress minus the remaining stress at a given time during a stress-relaxation test. (E28.11)

**remaining stress,** n—the stress remaining at a given time during a stress-relaxation test. (E28.11)

**stress relaxation**, *n*—the time-dependent decrease in stress in a solid under given constraint conditions. **(E28.11)** 

Discussion—Stress-relaxation tests are usually made under given constant total strain or deformation conditions.

**zero time,** *n*—the time when the given loading or constraint conditions are initially obtained in creep and stress-relaxation tests, respectively.

## F. BEARING (PIN) TESTS

**bearing area**  $[L^2]$ , n—the product of the pin diameter and specimen thickness. **(E28.04)** 

**bearing force** [F], *n*—a compressive force on an interface. (E28.04)

**bearing strain,** *n*—the ratio of the bearing deformation of the bearing hole, in the direction of the applied force, to the pin diameter. (E28.04)

**bearing strength** [FL $^{-2}$ ], n—the maximum bearing stress which a material is capable of sustaining. **(E28.04)** 

bearing stress [FL<sup>-2</sup>], n—the force per unit of bearing area. (E28.04)

**bearing yield strength** [FL<sup>-2</sup>], n—the bearing stress at which a material exhibits a specified limiting deviation from the proportionality of bearing stress to bearing strain. (**E28.04**)

**edge distance** [L], *n*—the distance from the edge of a bearing specimen to the center of the hole in the direction of applied force. (**E28.04**)

**edge distance ratio,** *n*—the ratio of the edge distance to the pin diameter. **(E28.04)** 

## **G. CALIBRATION**

**calibration**, *n*—determination of the values of the significant parameters by comparison with values indicated by a reference instrument or by a set of reference standards. (**E28.06**)

**calibration factor,** *n*—the factor by which the change in extensometer reading must be multiplied to obtain the equivalent strain. (**E28.01**)

Discussion—For any extensometer, the calibration factor is equal to the ratio of change in length to the product of the gage length and the change in extensometer reading. For direct-reading extensometers the calibration factor is unity.

**compressometer,** *n*—a specialized extensometer used for sensing negative or compressive strain. (E28.01)

**deflectometer,** *n*—a specialized extensometer used for sensing of extension or motion, usually without reference to a specific gage length. **(E28.01)** 

extensometer, n—a device for sensing strain. (E28.01)

**extensometer system,** *n*—a system for sensing and indicating strain. **(E28.01)** 

Discussion—The system will normally include an extensometer, conditioning electronics, and auxiliary device (recorder, digital readout, computer, etc.). However, completely self-contained mechanical devices are permitted. An extensometer system may be one of three types.

Type 1 extensometer system, n— an extensometer system that both defines gage length and senses extension; for example, a clip-on strain gage type with conditioning electronics. (E28.01)

Type 2 extensioneter system, n—, an extensioneter system that senses extension of a gage length that is defined by specimen features such as ridges, notches, or overall height (in case of a compression test piece). (E28.01)

Discussion—The precision associated with gage length setting for a Type 2 extensometer should be specified in relevant test method or product standard. The position readout on a testing machine is not recommended for use in a Type 2 extensometer system.

Type 3 extensometer system, n—an extensometer system that intrinsically senses strain (ratiometric principle); for example, video camera system. (E28.01)

**gage length** [L], *n*—the original length of that portion of the specimen over which strain or change of length is determined. (**E28.01**)



Discussion—When sensing extension or motion with a gage length that is predetermined by the specimen geometry or specific test method, then only resolution and strain error for the specified gage length should determine the class of the extensometer system.

**verification,** *n*—checking or testing to assure conformance with the specification. (E28.06)

# 5. Keywords

5.1 abbreviations; bearing; bend; compression; creep; ductility; foil; hardness; mechanical; pin; relaxation; shear; specifications; stress; symbols; tension; terms; testing; torsion

#### APPENDIX

(Nonmandatory Information)

## X1. SYMBOLS AND ABBREVIATIONS

X1.1 The following symbols and abbreviations are frequently used instead of or along with the terms covered by these definitions. For stress, the use of S with appropriate lower case subscripts is preferred for general purposes; for mathematical analysis the use of Greek symbols is generally preferred.3

area of cross section Α

distance from centroid to outermost fiber

D diameter

d diameter or diagonal

DPH diamond pyramid hardness (use HV, Vickers hardness number)

Ε modulus of elasticity in tension or compression

F force

G modulus of elasticity in shear

HB Brinell hardness number ΗK Knoop hardness number

Rockwell hardness number (requires scale designation) HR

HV Vickers hardness number moment of inertia

polar moment of inertia

lenath L

Μ bending moment

concentrated load

nominal engineering stress, or

S normal engineering stress

shear engineering stress

compressive engineering stress compressive yield strength

tensile engineering stress

 $S_a$   $S_c$   $S_c$   $S_t$   $S_u$   $S_y$  Ttensile strenath

yield strength

temperature, torque, or twisting moment

time

W work or energy

force per unit distance or per unit area

wΑ total distributed force for a given area

total distributed force for a given length wL

YPE yield point elongation

YS yield strength

section modulus3

increment Δ

deviation

true strain

shear strain Poisson's ratio<sup>A</sup>

normal true stress, nominal true stress<sup>B</sup> σ

compressive true stress

 $\sigma_{t}$ tensile true stress

shear true stress

angle of twist per unit length

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radius

 $<sup>^{</sup>A}\nu$  (nu) is preferred in applied mechanics. <sup>B</sup>Symbol confusion could result when statistical treatments are involved.

<sup>&</sup>lt;sup>3</sup> Many handbooks use S for section modulus, but Z is preferred since S is so widely used for normal or nominal stress.